

**October the 2nd, 2024, Gent, Belgium**

# Timoteo Carletti

## Global synchronization on networks and beyond



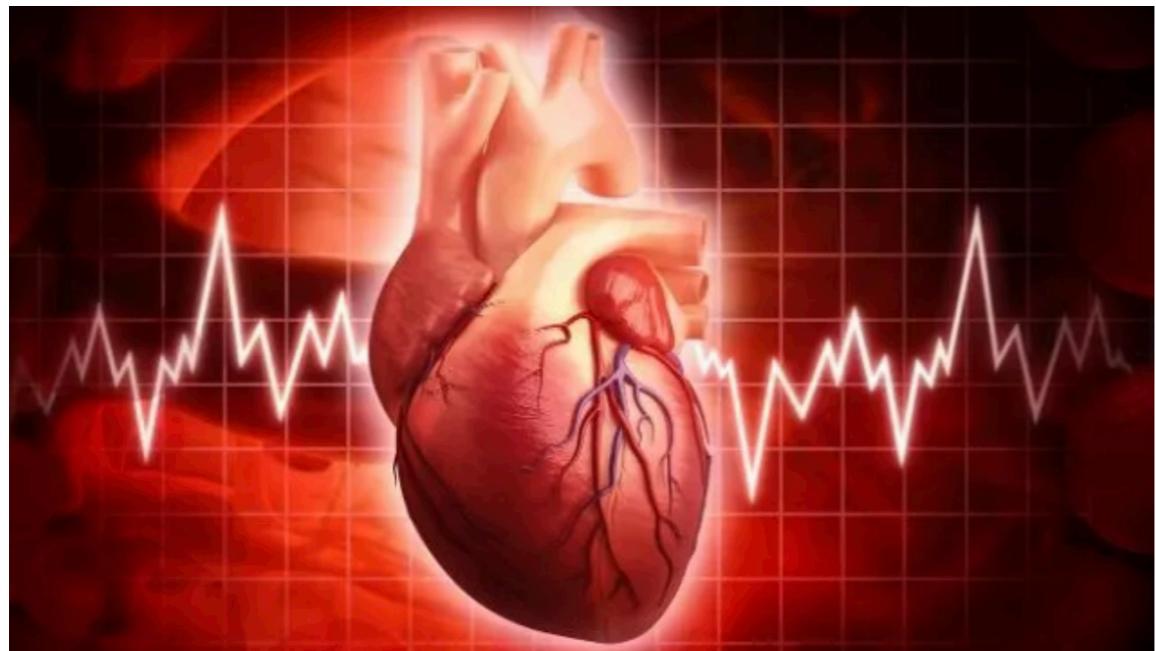
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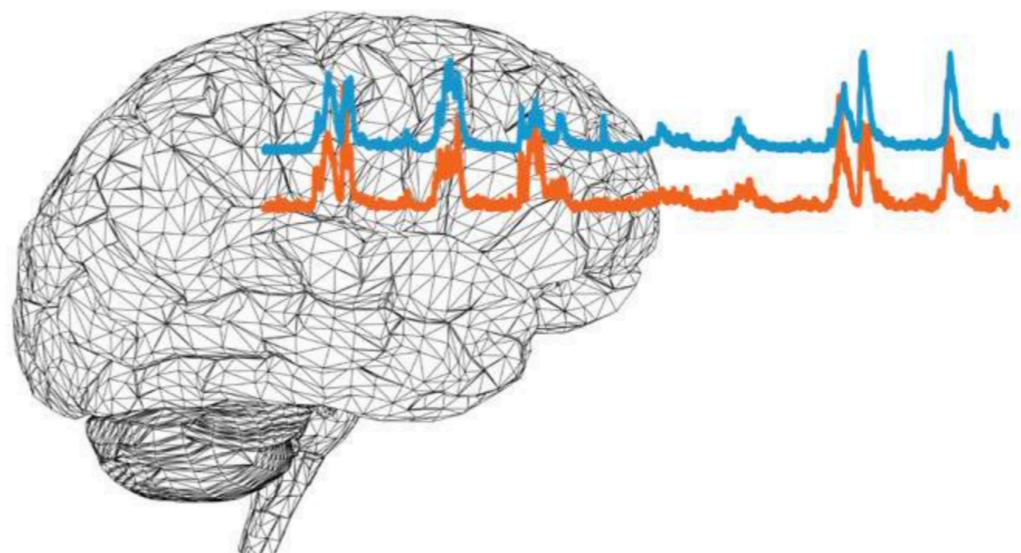
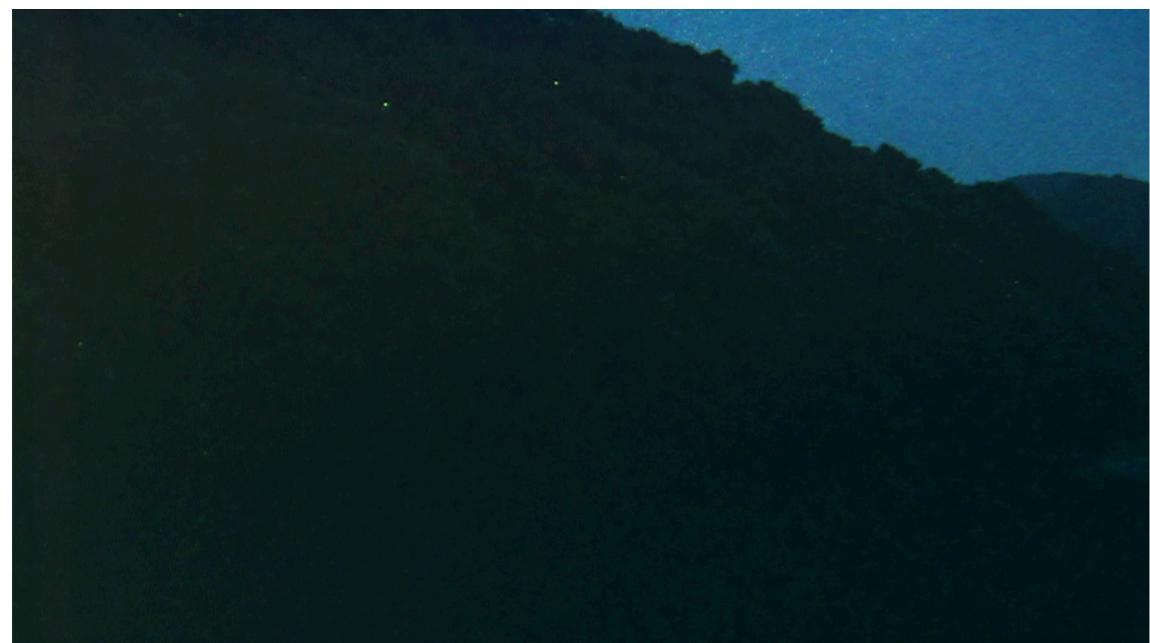


**naxys**  
Namur Center for Complex Systems

# Synchronisation

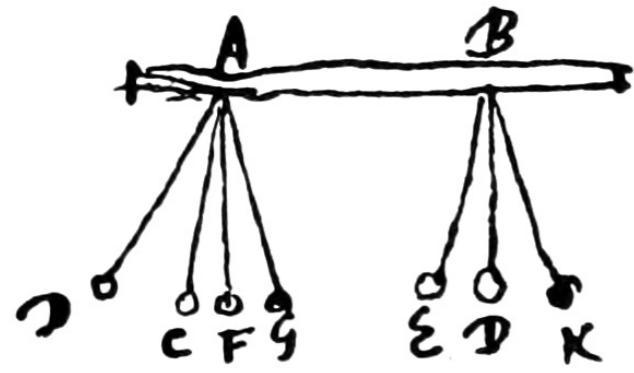
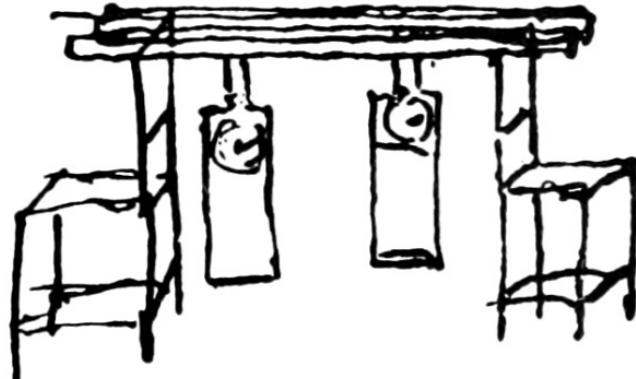


[www.youtube.com](http://www.youtube.com)



[www.quantamagazine.org](http://www.quantamagazine.org)

# Global Synchronisation



[www.youtube.com](http://www.youtube.com)

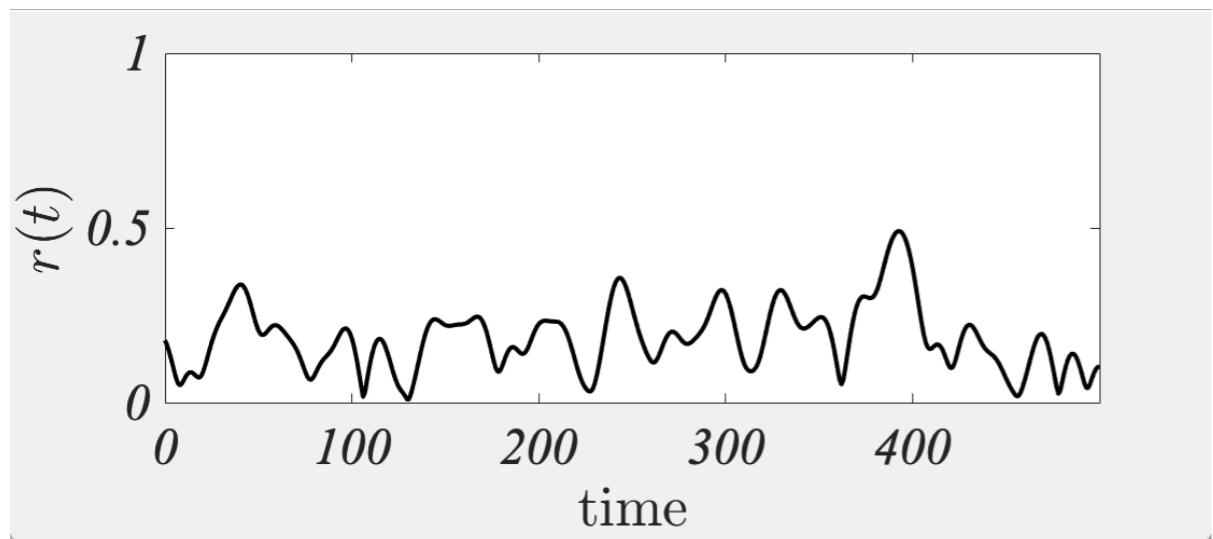
Huygen

"An odd kind of sympathy"

# Kuramoto model

$$\frac{d\theta_i}{dt} = \omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_j - \theta_i)$$

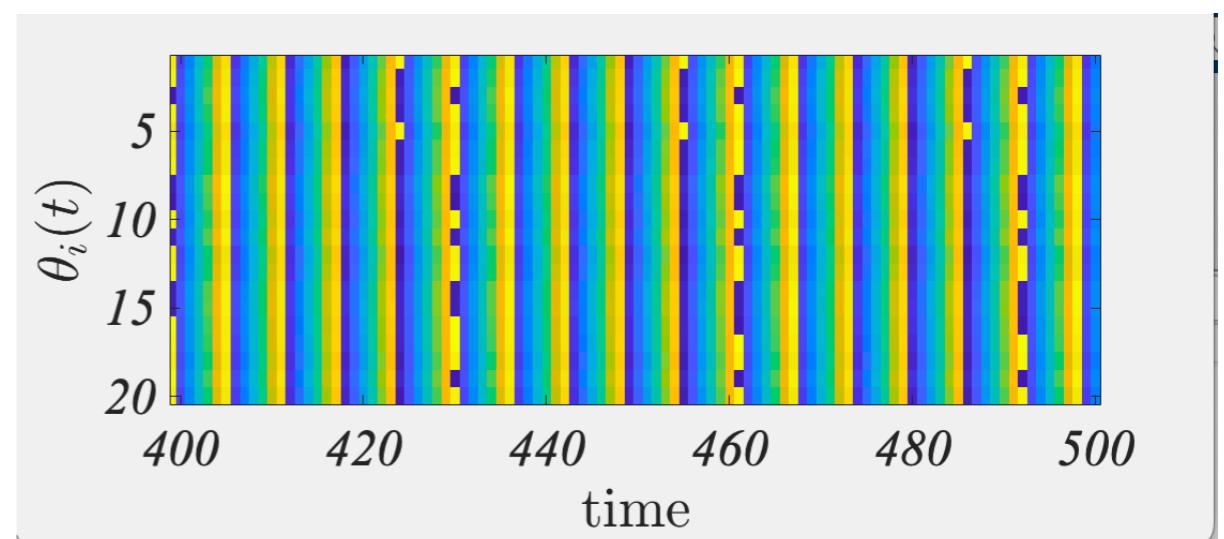
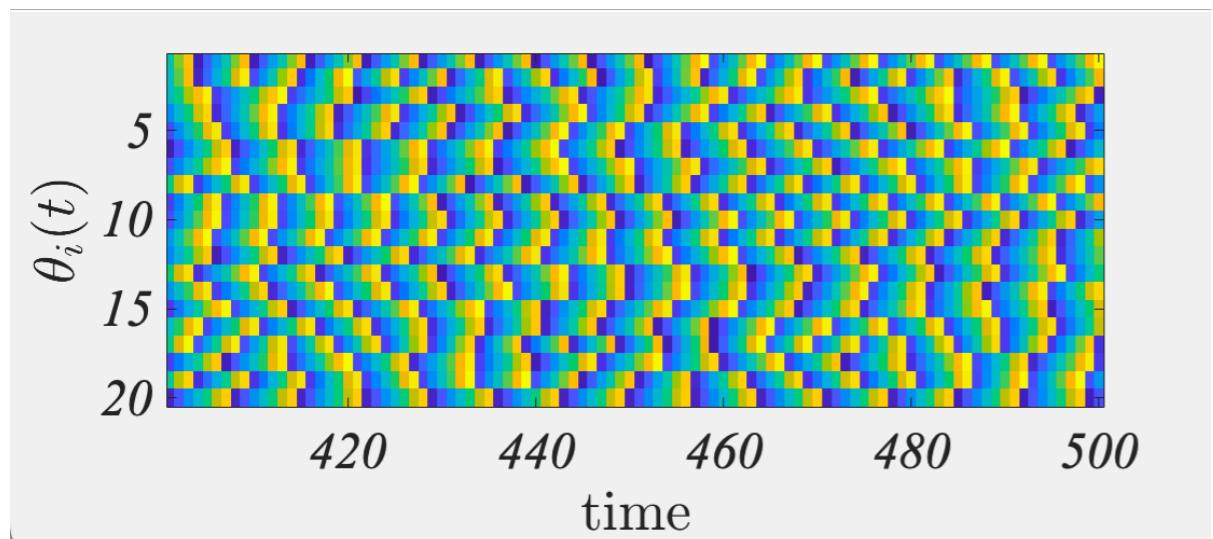
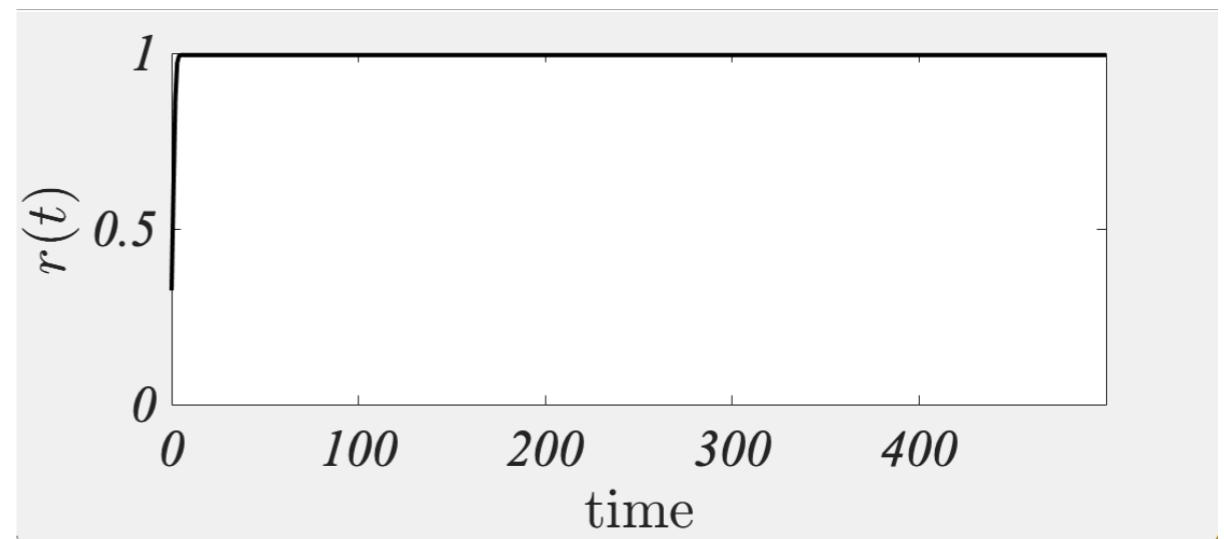
$$K = 0.01$$



order parameter

$$re^{i\psi} = \frac{1}{N} \sum_{j=1}^N e^{i\theta_j}$$

$$K = 1.0$$



# Global Synchronisation

Progress of Theoretical Physics, Vol. 69, No. 1, January 1983

## Stability Theory of Synchronized Motion in Coupled-Oscillator Systems

Hirokazu FUJISAKA and Tomoji YAMADA\*

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\**Department of Physics, Kyushu Institute of Technology  
Kitakyushu 804*

VOLUME 64, NUMBER 8

PHYSICAL REVIEW LETTERS

19 FEBRUARY 1990

## Synchronization in Chaotic Systems

Louis M. Pecora and Thomas L. Carroll

*Code 6341, Naval Research Laboratory, Washington, D.C. 20375*

(Received 20 December 1989)

VOLUME 80, NUMBER 10

PHYSICAL REVIEW LETTERS

9 MARCH 1998

## Master Stability Functions for Synchronized Coupled Systems

Louis M. Pecora and Thomas L. Carroll

*Code 6343, Naval Research Laboratory, Washington, D.C. 20375*

(Received 7 July 1997)

PHYSICAL REVIEW E 80, 036204 (2009)

## Generic behavior of master-stability functions in coupled nonlinear dynamical systems

Liang Huang,<sup>1</sup> Qingfei Chen,<sup>1</sup> Ying-Cheng Lai,<sup>1,2</sup> and Louis M. Pecora<sup>3</sup>

<sup>1</sup>*School of Electrical, Computer and Energy Engineering, Arizona State University, Tempe, Arizona 85287, USA*

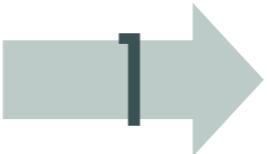
<sup>2</sup>*Department of Physics, Arizona State University, Tempe, Arizona 85287, USA*

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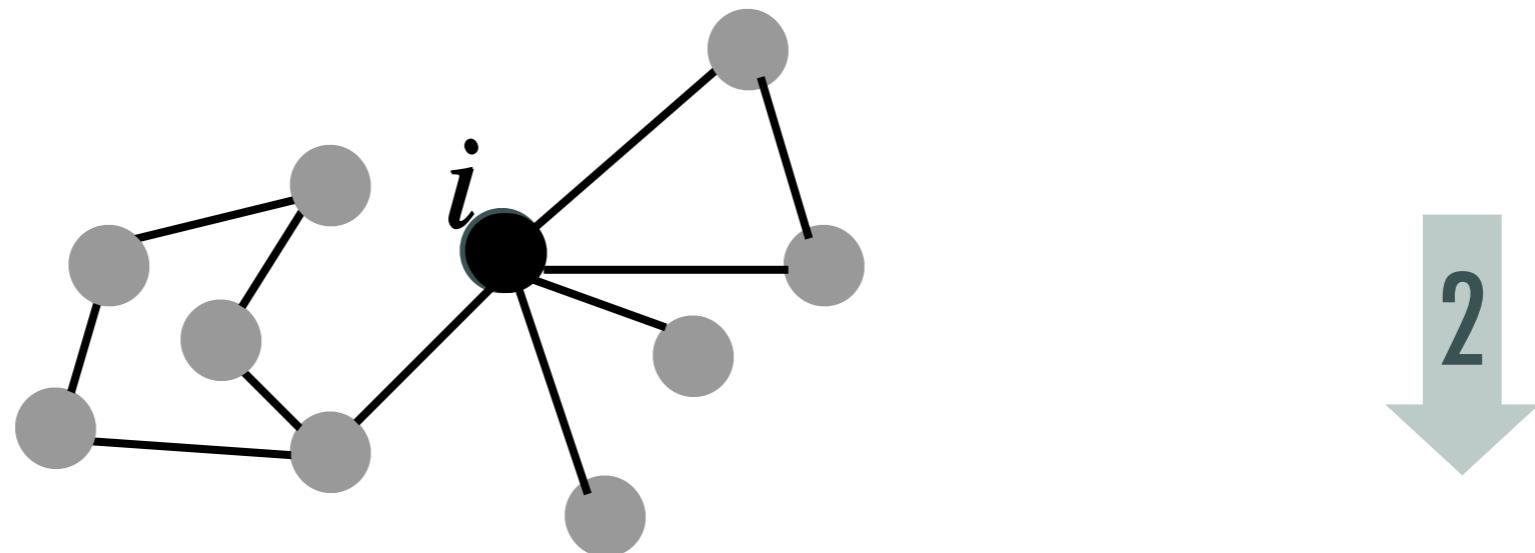
(Received 9 June 2009; published 15 September 2009)

# Global Synchronisation on networks

$$\frac{d\mathbf{x}}{dt} = \mathbf{f}(\mathbf{x}) \quad \mathbf{x} \in \mathbb{R}^d$$



$$\frac{d\mathbf{x}^{(i)}}{dt} = \mathbf{f}(\mathbf{x}^{(i)}) \quad \mathbf{x}^{(i)} \in \mathbb{R}^d$$
$$i = 1, \dots, n$$



$$\frac{d\mathbf{x}^{(i)}}{dt} = \mathbf{f}(\mathbf{x}^{(i)}) + \sigma \sum_{j=1}^n A_{ij} \mathbf{g}(\mathbf{x}^{(i)}, \mathbf{x}^{(j)})$$

$$\mathbf{g}(\mathbf{x}^{(i)}, \mathbf{x}^{(j)}) = \mathbf{h}(\mathbf{x}^{(j)}) - \mathbf{h}(\mathbf{x}^{(i)})$$

$$= \mathbf{f}(\mathbf{x}^{(i)}) + \sigma \sum_{j=1}^n L_{ij} \mathbf{h}(\mathbf{x}^{(j)})$$

Diffusive-like coupling

$$L_{ij} = A_{ij} - \delta_{ij} k_i$$

# Global Synchronisation on networks

Reference orbit  $\mathbf{s}(t)$  solution of  $\frac{d\mathbf{s}}{dt} = \mathbf{f}(\mathbf{s})$

Global Synchronisation :  $\mathbf{x}^{(i)}(t) = \mathbf{s}(t) \quad \forall i = 1, \dots, n$

Does the whole system admit such (spatially) homogeneous solution?

♣  $\frac{d\mathbf{x}^{(i)}}{dt} \Big|_{\mathbf{x}^{(i)}=\mathbf{s}} = \mathbf{f}(\mathbf{x}^{(i)}) + \sigma \sum_{j=1}^n L_{ij} \mathbf{h}(\mathbf{x}^{(j)}) \Big|_{\mathbf{x}^{(i)}=\mathbf{s}} = 0$

$$\mathbf{L}\mathbf{u} = 0 \quad \mathbf{u} = (1, \dots, 1)^\top$$

Laplace matrix

# Global Synchronisation on networks

Is  $\mathbf{x}^{(i)}(t) = \mathbf{s}(t)$   $\forall i = 1, \dots, n$  stable?

⊗  $\delta\mathbf{x}^{(i)}(t) = \mathbf{x}^{(i)}(t) - \mathbf{s}(t) \quad \forall i = 1, \dots, n$

⊗  $\frac{d\delta\mathbf{x}^{(i)}}{dt} = \mathbf{J}_f(\mathbf{s}(t))\delta\mathbf{x}^{(i)} + \sigma \sum_{j=1}^n L_{ij} \mathbf{J}_h(\mathbf{s}(t))\delta\mathbf{x}^{(j)}$

Time dependent linear system

# Global Synchronisation on networks

♣  $\mathbf{L}\phi^{(\alpha)} = \Lambda^{(\alpha)}\phi^{(\alpha)}$      $\phi^{(\alpha)} \cdot \phi^{(\beta)} = \delta_{\alpha\beta}$      $\Lambda^{(1)} = 0$      $\Lambda^{(\alpha)} < 0$

♣  $\delta\mathbf{x}^{(i)} = \sum_{\alpha} \delta\mathbf{x}_{\alpha} \phi_i^{(\alpha)}$

♣  $\frac{d\delta\mathbf{x}_{\alpha}}{dt} = \mathbf{J_f}(\mathbf{s}(t))\delta\mathbf{x}_{\alpha} + \sigma\Lambda^{(\alpha)}\mathbf{J_h}(\mathbf{s}(t))\delta\mathbf{x}_{\alpha} := \mathbf{J}_{\alpha}(\mathbf{s}(t))\delta\mathbf{x}_{\alpha}$

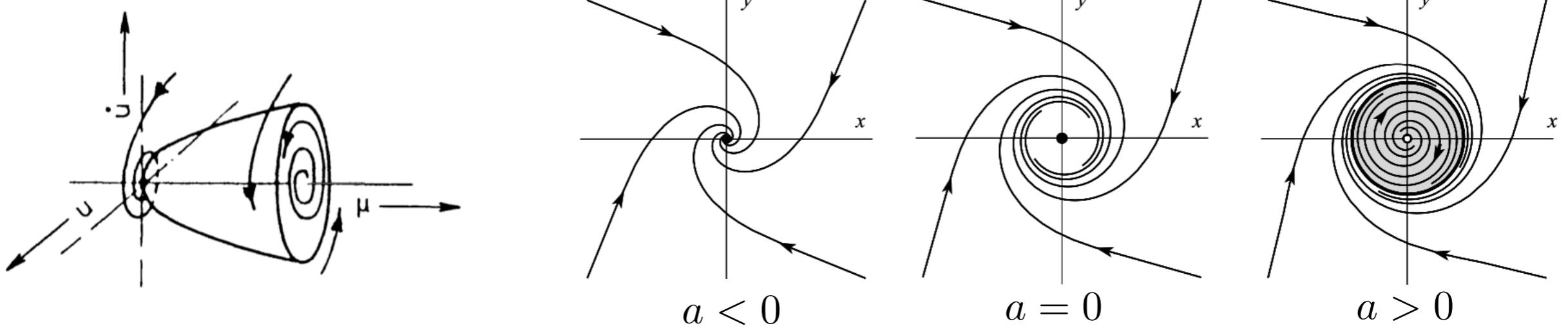
$\lambda(\Lambda^{(\alpha)})$  **Master Stability Function = largest Lyapunov exponent of  $\mathbf{J}_{\alpha}(\mathbf{s}(t))$**

**(function of  $\Lambda^{(\alpha)}$  eigenvalue of L )**

# Stuart - Landau oscillator

$$\frac{dz}{dt} = z(a + ib - |z|^2) \quad z = x + iy \in \mathbb{C} \quad a \in \mathbb{R} \quad b \in \mathbb{R}_+$$

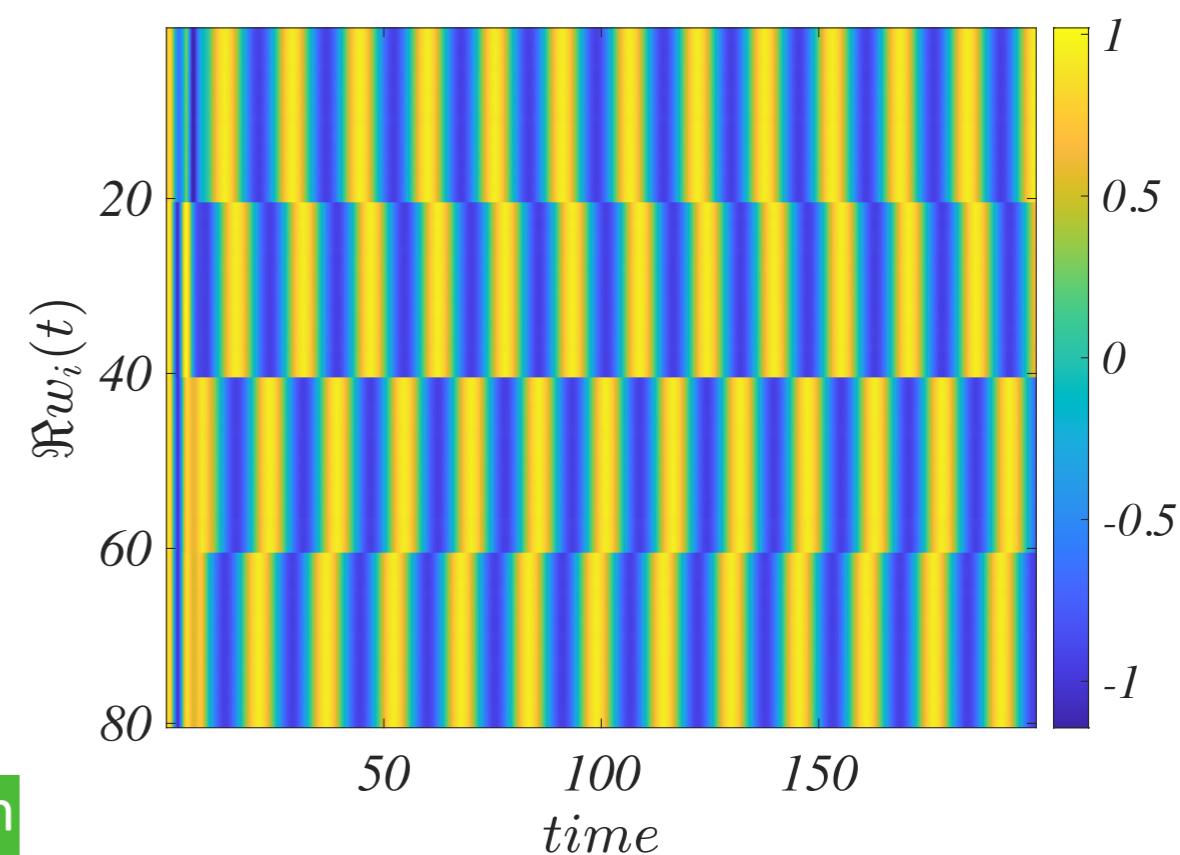
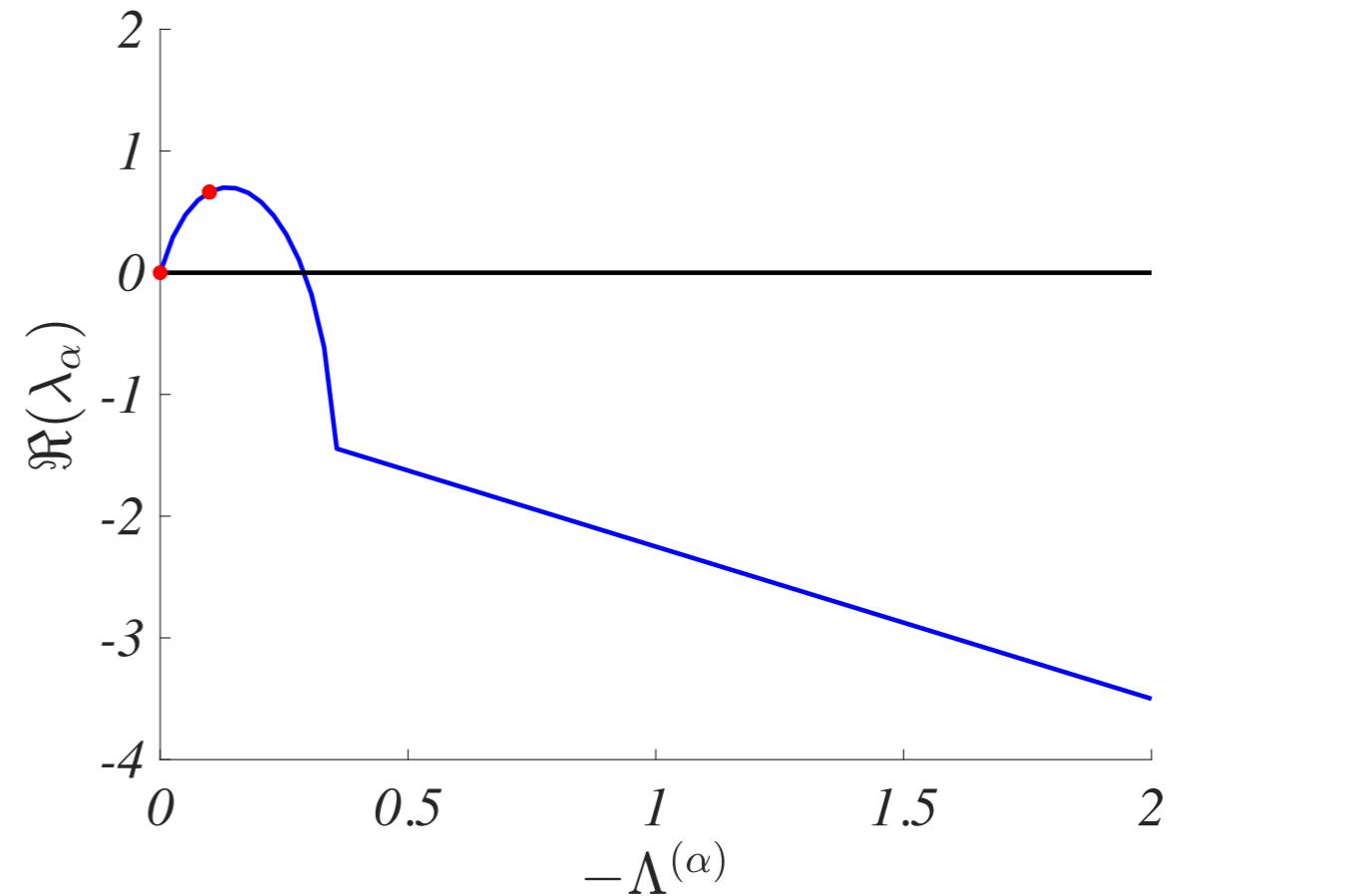
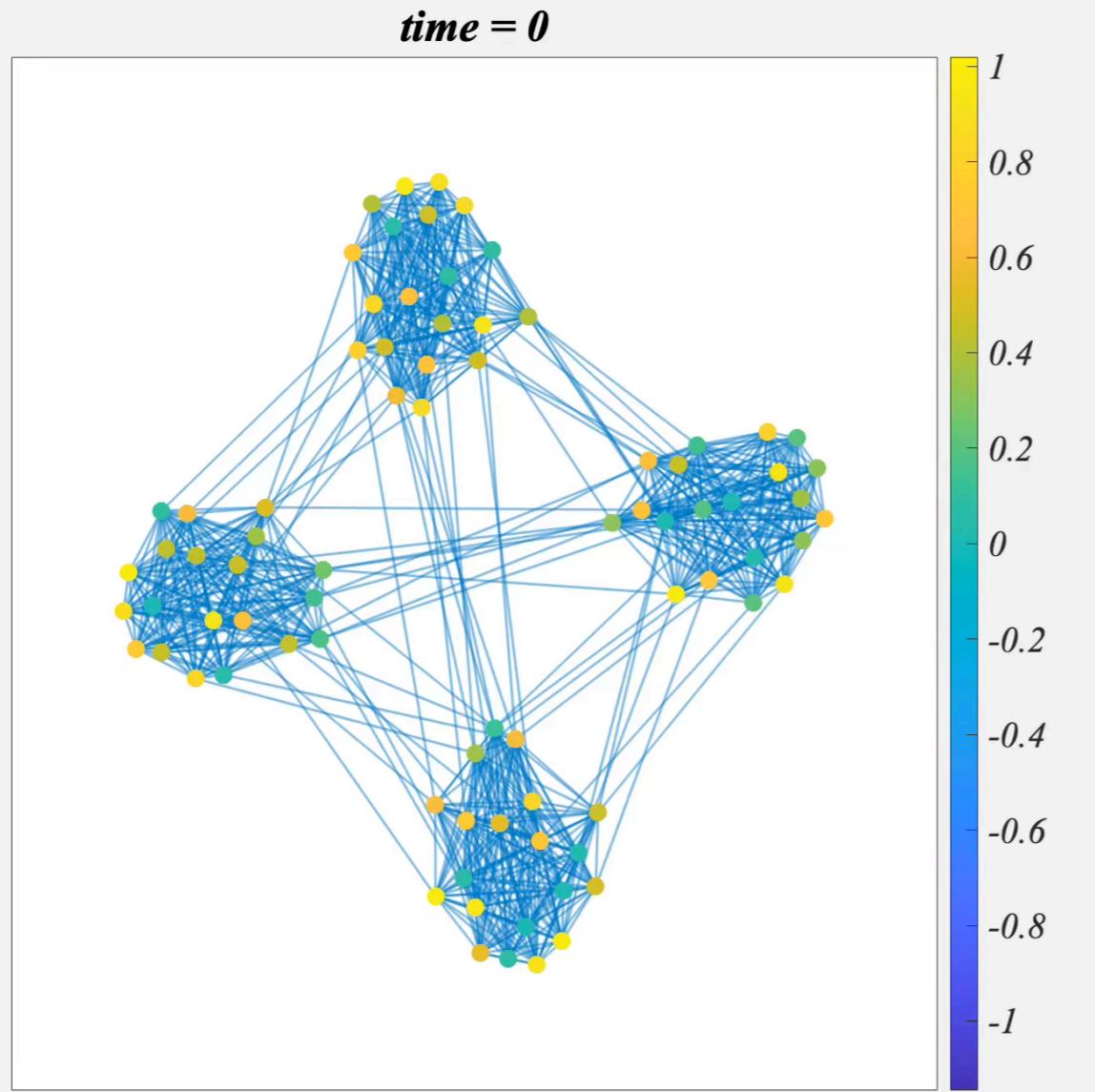
## Hopf Bifurcation



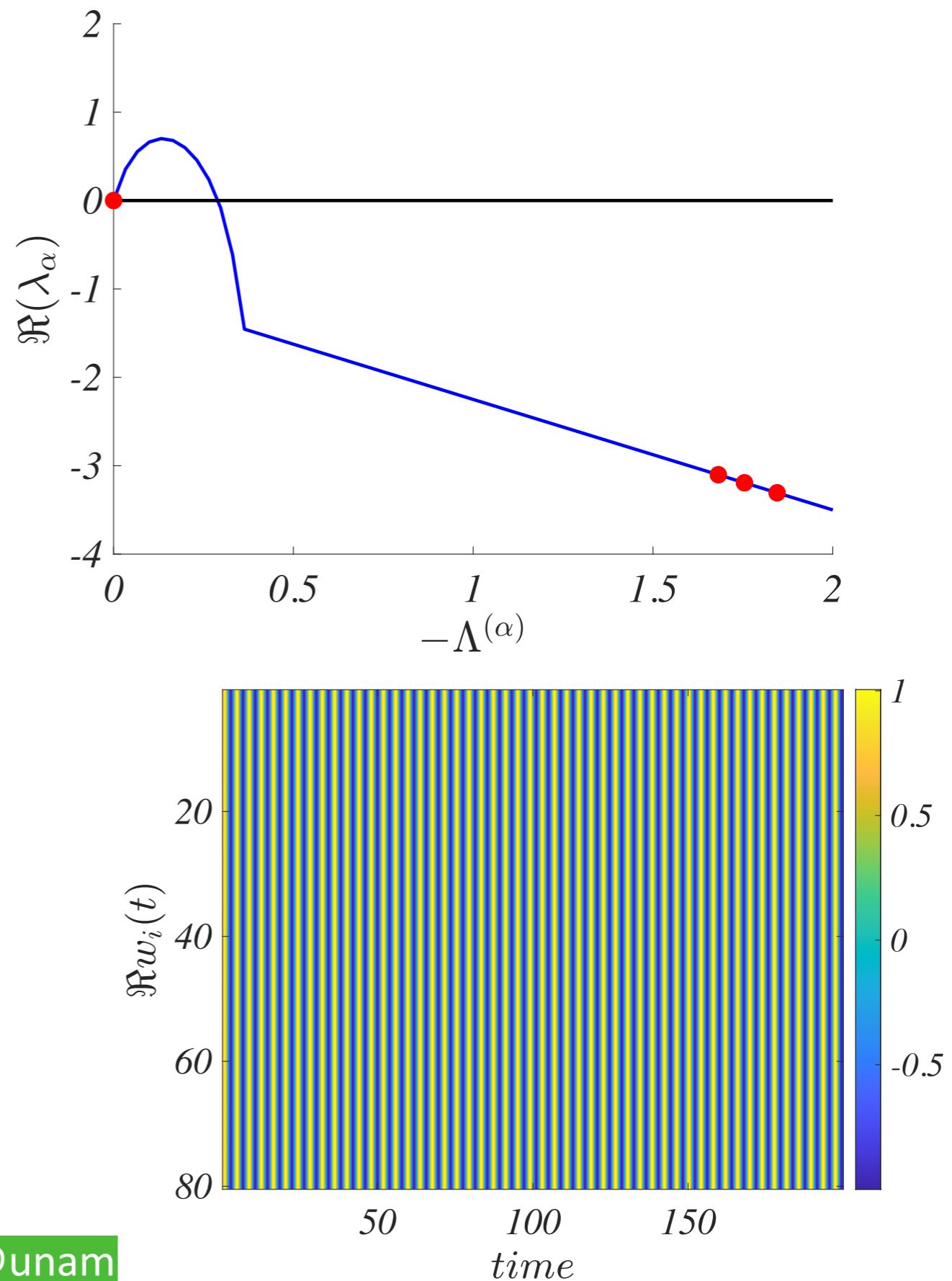
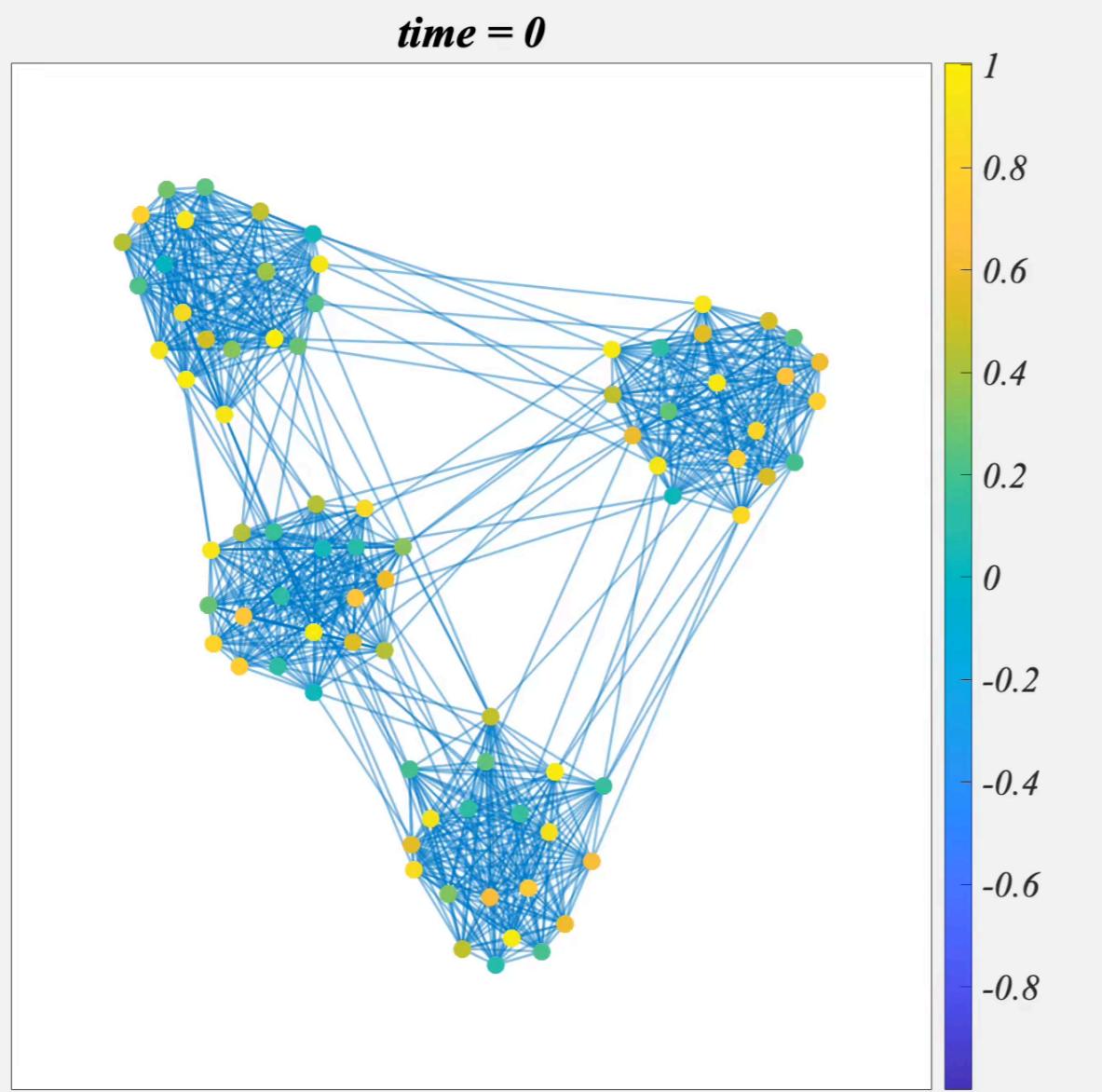
$$\frac{dz_j}{dt} = z_j(a + ib - |z_j|^2) + \mu \sum_{j=1}^n A_{j\ell} [h(z_\ell) - h(z_j)]$$

$$h(z) = |z|^{m-1} z$$

# Stuart - Landau oscillator : no synch

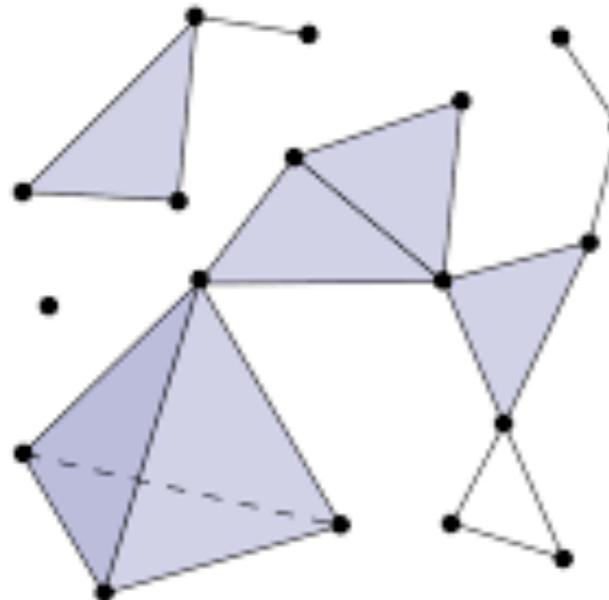


# Stuart - Landau oscillator : synch



# Simplicial complexes and Hypergraphs

## Simplicial complexes



d-simplex =  $d+1$  nodes

(all linked together)

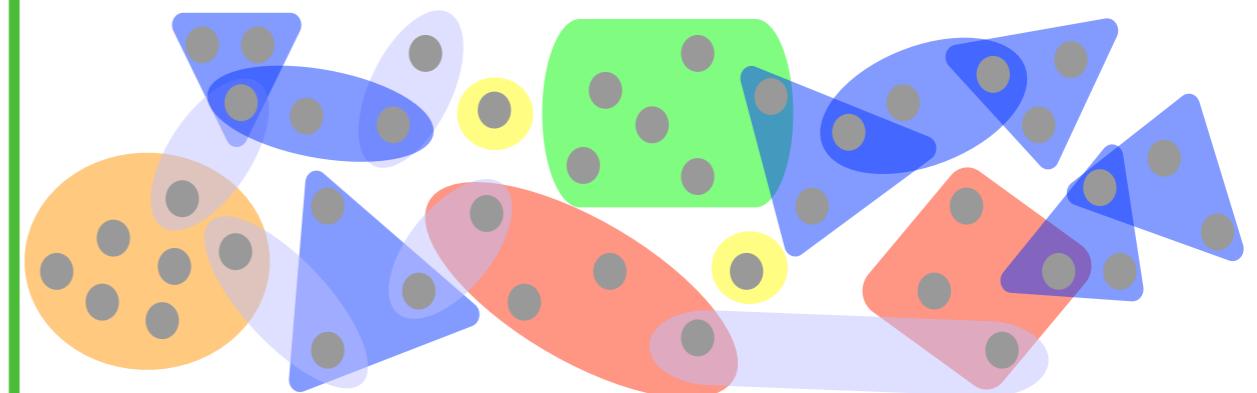
0-simplex = node

1-simplex = link

2-simplex = triangle

3-simplex = tetrahedron

## Hypergraphs



hyperedge = set of nodes

## Journal of Physics: Complexity

OPEN ACCESS

PAPER



CrossMark

### Dynamical systems on hypergraphs

RECEIVED

2 June 2020

REVISED

9 July 2020

ACCEPTED FOR PUBLICATION

23 July 2020

PUBLISHED

17 August 2020

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<sup>4</sup> Author to whom any correspondence should be addressed.

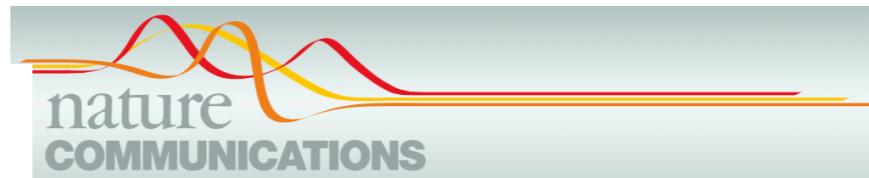
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**Keywords:** hypergraphs, master stability function, synchronisation, Turing patterns, dynamical systems

# Global Synchronisation : beyond networks

$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i) + \sigma_1 \sum_{j=1}^N a_{ij}^{(1)} \mathbf{g}^{(1)}(\mathbf{x}_i, \mathbf{x}_j)$$

$$+ \sigma_2 \sum_{j=1}^N \sum_{k=1}^N a_{ijk}^{(2)} \mathbf{g}^{(2)}(\mathbf{x}_i, \mathbf{x}_j, \mathbf{x}_k),$$



ARTICLE

<https://doi.org/10.1038/s41467-021-21486-9>

OPEN

## Stability of synchronization in simplicial complexes

L. V. Gambuzza<sup>1,12</sup>, F. Di Patti<sup>1</sup>, L. Gallo<sup>1</sup>, S. Lepri<sup>2</sup>, M. Romance<sup>1</sup>, R. Criado<sup>5</sup>, M. Frasca<sup>1,6,13</sup>, V. Latora<sup>1</sup> & S. Boccaletti<sup>2,9,10,11,13</sup>

Check for updates

## Synchronisation non invasive

$$\mathbf{g}^{(d)}(\mathbf{x}, \mathbf{x}, \dots, \mathbf{x}) \equiv 0 \quad \forall d$$

$$\begin{cases} \dot{\eta}_1 = JF\eta_1 \\ \dot{\eta}_i = (JF - \sigma_1 \lambda_i JG^{(1)})\eta_i - \sigma_2 \sum_{j=2}^N \tilde{\mathcal{L}}_{ij}^{(2)} JG^{(2)}\eta_j, \end{cases}$$

i) Assumptions on  $\mathbf{g}^{(2)}$   
ii) Assumptions on  $a_{ijk}^{(2)}$

# Global Synchronisation time varying higher-order networks

*J. Phys. Complex.* **5** (2024) 015020

<https://doi.org/10.1088/2632-072X/ad3262>

## Journal of Physics: Complexity

PAPER

### Global synchronization on time-varying higher-order structures

Md Sayeed Anwar<sup>1</sup> , Dibakar Ghosh<sup>1</sup>  and Timoteo Carletti<sup>2,\*</sup> 

$$\dot{\vec{x}}_i = \vec{f}(\vec{x}_i) + \sum_{d=1}^D q_d \sum_{j_1, \dots, j_d=1}^n A_{ij_1 \dots j_d}^{(d)}(t) \vec{g}^{(d)}(\vec{x}_i, \vec{x}_{j_1}, \dots, \vec{x}_{j_d})$$

# Global Topological Synchronisation

PHYSICAL REVIEW LETTERS **130**, 187401 (2023)

Editors' Suggestion

## Global Topological Synchronization on Simplicial and Cell Complexes

Timoteo Carletti<sup>ID</sup>,<sup>1</sup> Lorenzo Giambagli<sup>ID</sup>,<sup>1,2</sup> and Ginestra Bianconi<sup>ID</sup>,<sup>3,4</sup>

<sup>1</sup>*Department of Mathematics and naXys, Namur Institute for Complex Systems, University of Namur,  
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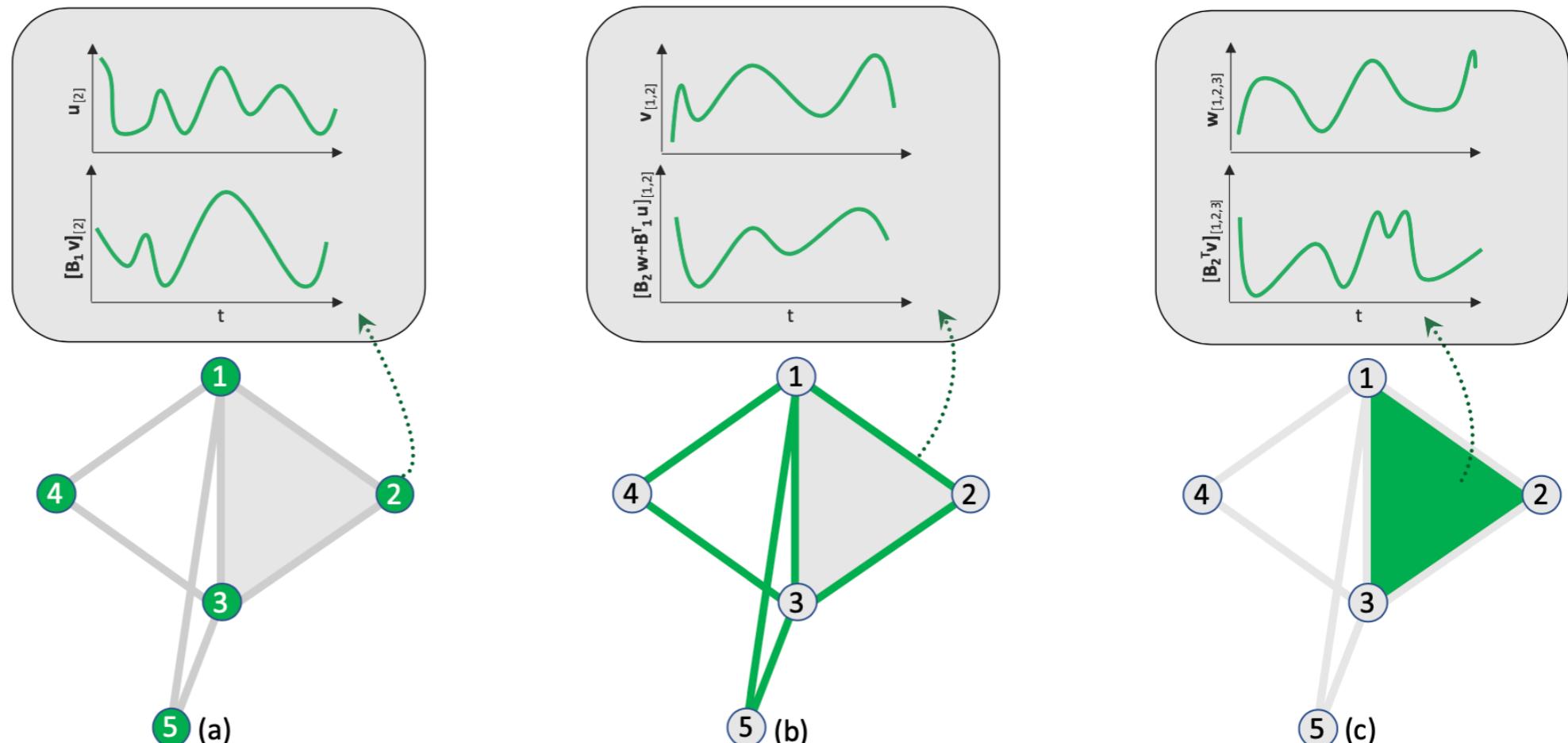
<sup>2</sup>*Department of Physics and Astronomy, University of Florence, INFN and CSDC, 50019 Sesto Fiorentino, Italy*

<sup>3</sup>*School of Mathematical Sciences, Queen Mary University of London, London, E1 4NS, United Kingdom*

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(Received 31 August 2022; revised 17 February 2023; accepted 11 April 2023; published 3 May 2023)

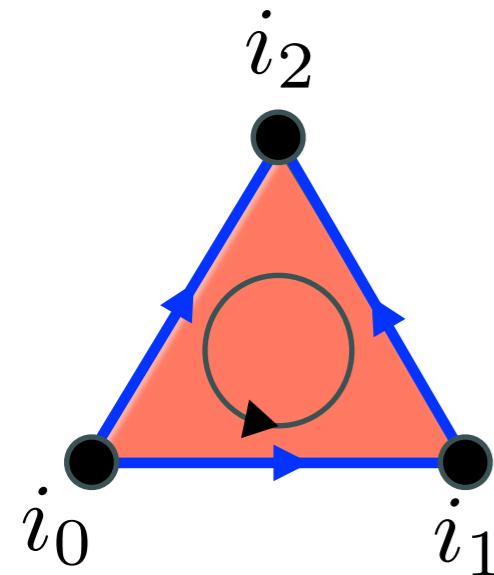


# Simplicial complex: an example

$$k = 2$$

Three nodes, hence a triangle

$$\sigma^{(2)} = [i_0, i_1, i_2]$$



Incidence matrices

$$\mathbf{B}_1 \in M^{N_0 \times N_1}$$

$$\sigma_1^{(1)} = [i_0, i_1] \quad \sigma_2^{(1)} = [i_1, i_2] \quad \sigma_3^{(1)} = [i_0, i_2]$$

$$\mathbf{B}_1(\sigma_i^{(0)}, \sigma_j^{(1)}) = \begin{matrix} & [i_0, i_1] & [i_1, i_2] & [i_0, i_2] \\ i_0 & -1 & 0 & -1 \\ i_1 & 1 & -1 & 0 \\ i_2 & 0 & 1 & 1 \end{matrix}$$

$$\mathbf{B}_2 \in M^{N_1 \times N_2}$$

$$\mathbf{B}_2(\sigma_i^{(1)}, \sigma_j^{(2)}) = \begin{matrix} [i_0, i_1] \\ [i_1, i_2] \\ [i_0, i_2] \end{matrix} \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

# Simplicial complexes

$$\sigma_i^{(k)} = [i_0, \dots, i_k]$$

$$B_k(\sigma_i^{(k-1)}, \sigma_j^{(k)}) = 1 \text{ if } \sigma_i^{(k-1)} \sim \sigma_j^{(k)}$$

$$\mathbf{B}_k \in M^{N_{k-1} \times N_k}$$

$$B_k(\sigma_i^{(k-1)}, \sigma_j^{(k)}) = -1 \text{ if } \sigma_i^{(k-1)} \not\sim \sigma_j^{(k)}$$

## Incidence matrix

$$B_k(\sigma_i^{(k-1)}, \sigma_j^{(k)}) = 0 \text{ otherwise}$$

$$\mathbf{L}_k = \mathbf{B}_k^\top \mathbf{B}_k + \mathbf{B}_{k+1} \mathbf{B}_{k+1}^\top$$

## Hodge Laplace matrix

# Dynamics on simplicial complexes

$$\sigma_i^{(k)} = [i_0, \dots, i_k]$$

$$\mathbf{x} : C_k \rightarrow \mathbb{R}^d \quad \text{k-cochain}$$

$$\mathbf{x}_i = \mathbf{x}(\sigma_i^{(k)}) = (x_i^1, \dots, x_i^d)$$

$$\mathbf{x}(-\sigma_i^{(k)}) = -\mathbf{x}(\sigma_i^{(k)})$$

## Dynamical system on a simplex

$$\frac{d\mathbf{x}_i}{dt} = \mathbf{f}(\mathbf{x}_i)$$

$$\mathbf{f}(-\mathbf{x}_i) = -\mathbf{f}(\mathbf{x}_i)$$

# Global Topological Synchronisation

## Dynamical system on a simplicial complex

$$\frac{d\mathbf{x}_i}{dt} = \mathbf{f}(\mathbf{x}_i) - \sigma \sum_{j=1}^{N_k} L_k(i, j) \mathbf{h}(\mathbf{x}_j) \quad \mathbf{h}(-\mathbf{x}_i) = -\mathbf{h}(\mathbf{x}_i)$$

Reference orbit  $\mathbf{s}(t)$  solution of  $\frac{d\mathbf{s}}{dt} = \mathbf{f}(\mathbf{s})$

Synchronisation :  $\mathbf{x}_i(t) = \mathbf{s}(t) \quad \forall i = 1, \dots, N_k$

$$\left. \frac{d\mathbf{x}_i}{dt} \right|_{\mathbf{x}_i=\mathbf{s}} = \mathbf{f}(\mathbf{x}_i) + \sigma \sum_{j=1}^n L_{ij} \mathbf{h}(\mathbf{x}_j) \Big|_{\mathbf{x}_i=\mathbf{s}} \stackrel{\bullet}{\neq} 0$$

# Global Topological Synchronisation

Necessary condition  $\mathbf{L}_k u = 0 \iff \mathbf{B}_k u = 0$  and  $\mathbf{B}_{k+1}^\top u = 0$

$$\sum_j B_k(\sigma_i^{(k-1)}, \sigma_j^{(k)}) = 0 \Rightarrow \sigma_i^{(k-1)} \text{ even numb incident } \sigma_j^{(k)}$$

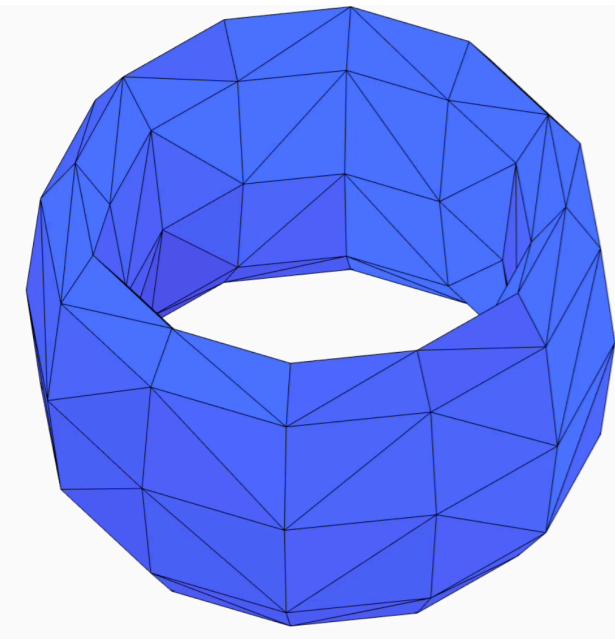
**half coherent / half incoherent**

Balanced simplicial complex

$$\sum_i B_{k+1}(\sigma_i^{(k)}, \sigma_j^{(k+1)}) = 0 \Rightarrow \sigma_j^{(k+1)} \text{ contains even numb } \sigma_i^{(k)}$$

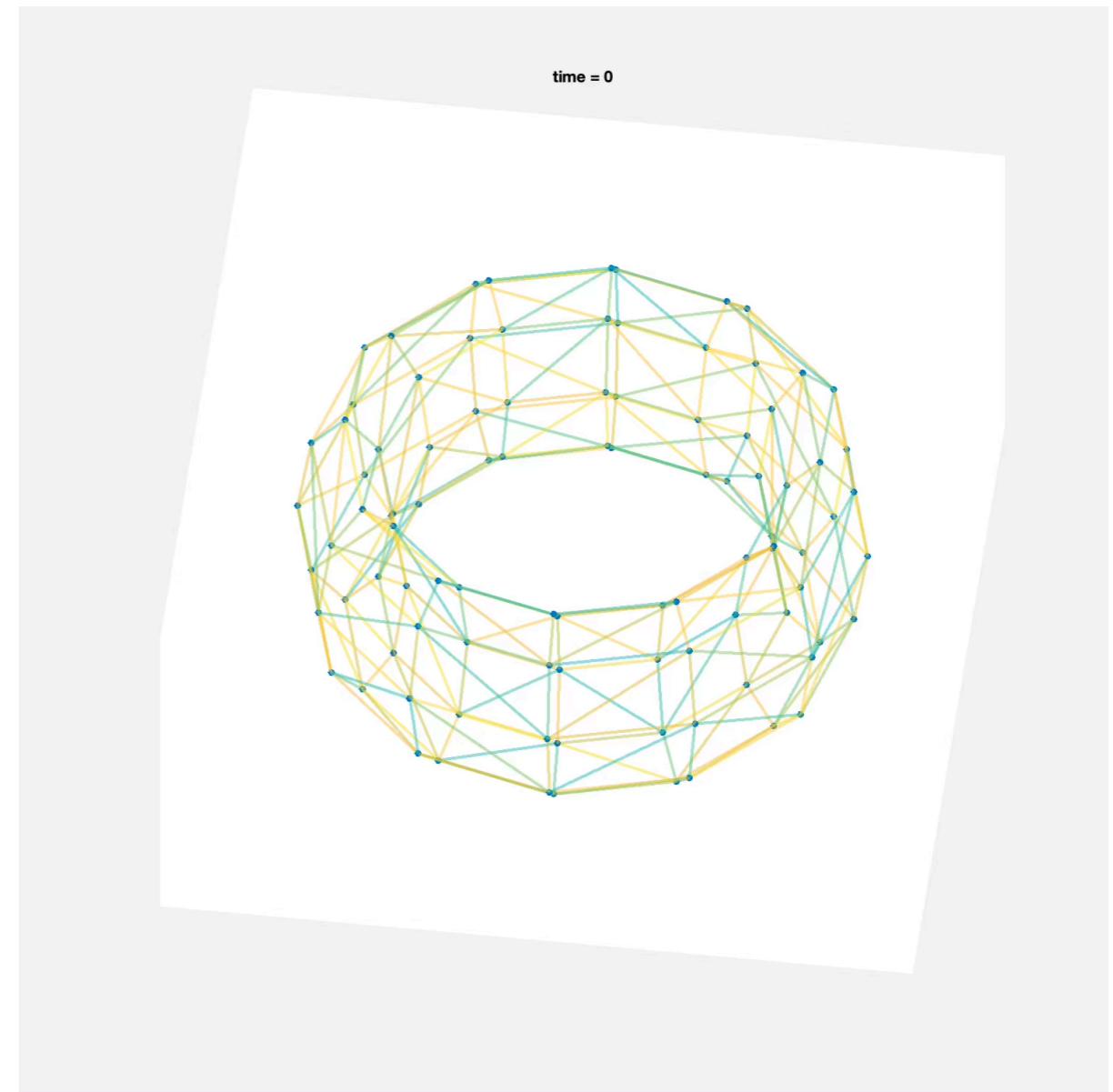
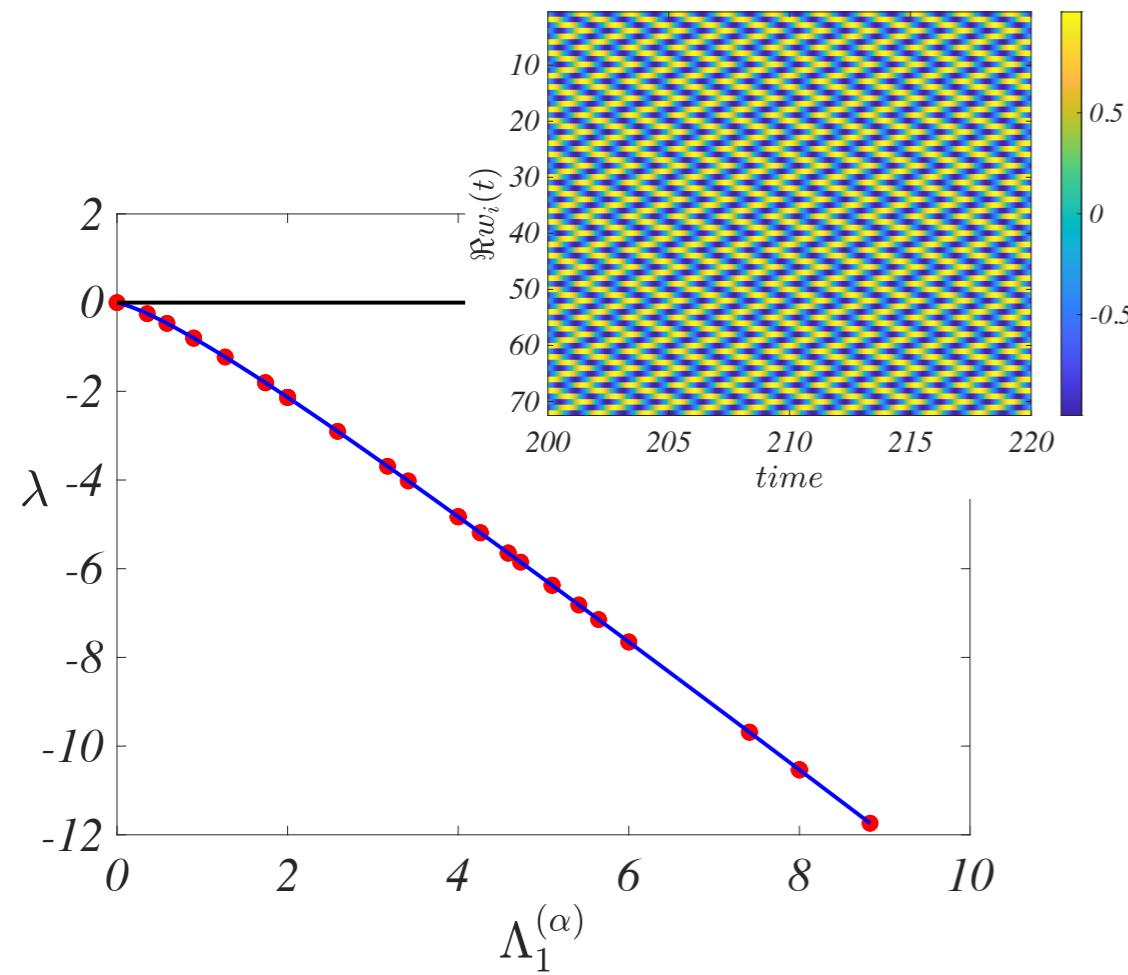
**impossible if k is odd**

# Global Topological Synchronisation : Stuart-Landau on 2D-triangulated torus

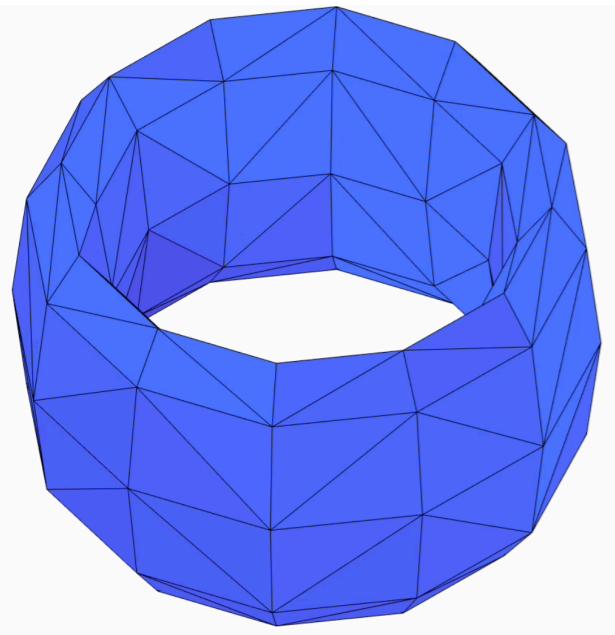


no global synch  
for links ( $k=1$ )

$$\mathbf{B}_1(1, \dots, 1)^\top = 0$$
$$\mathbf{B}_2^\top(1, \dots, 1)^\top \neq 0$$



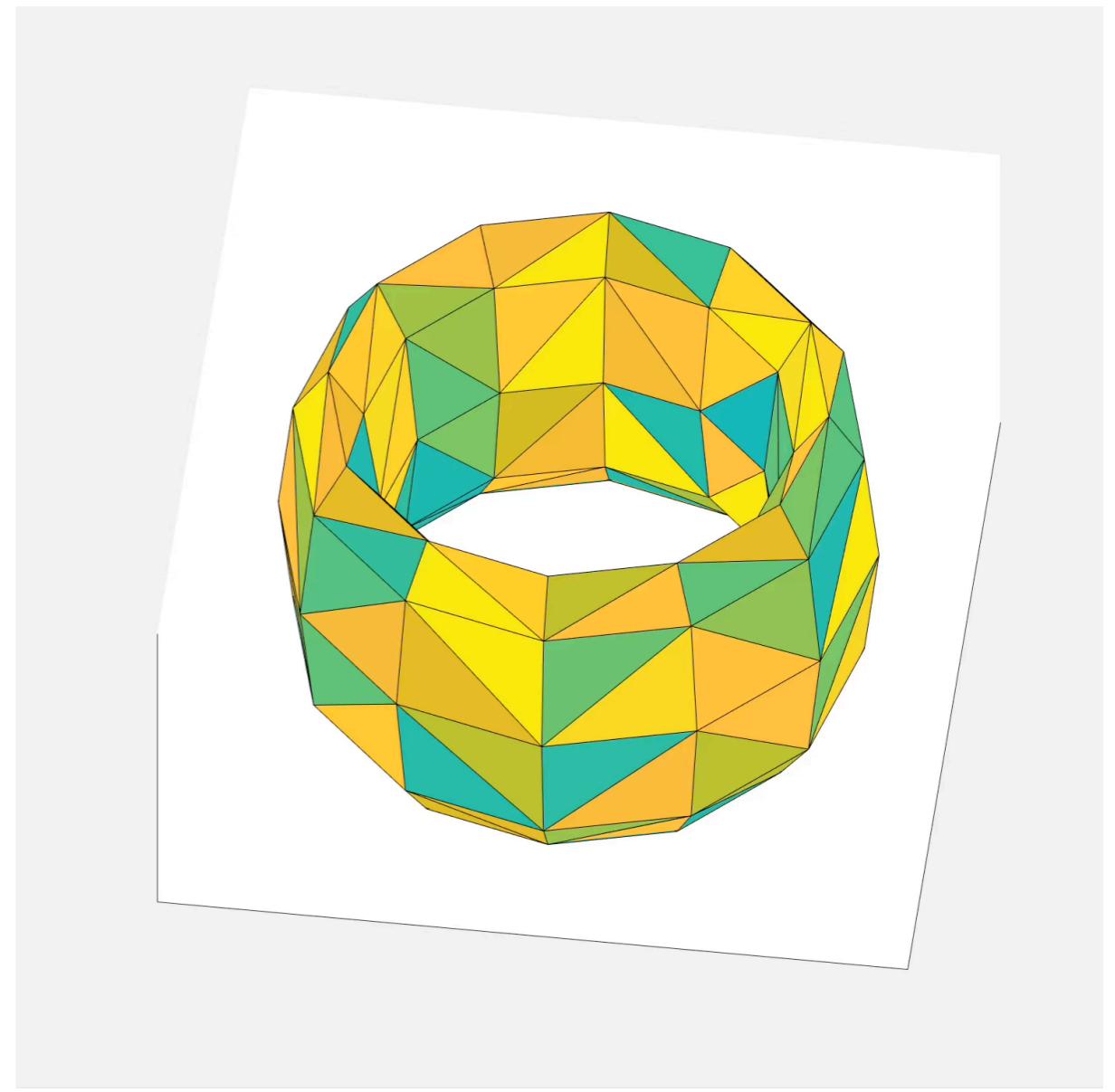
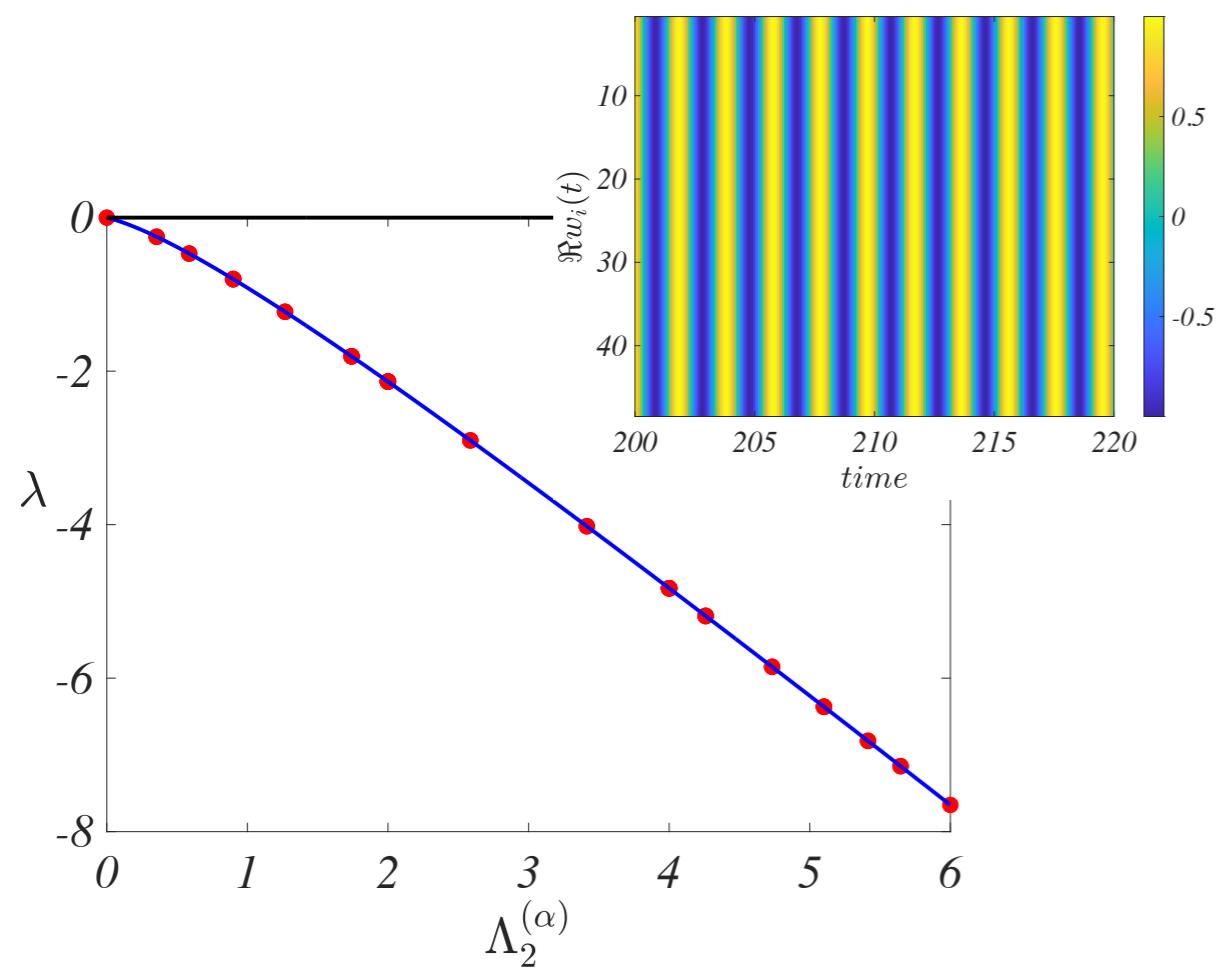
# Global Topological Synchronisation : Stuart-Landau on 2D-triangulated torus



global synch  
for faces (k=2)

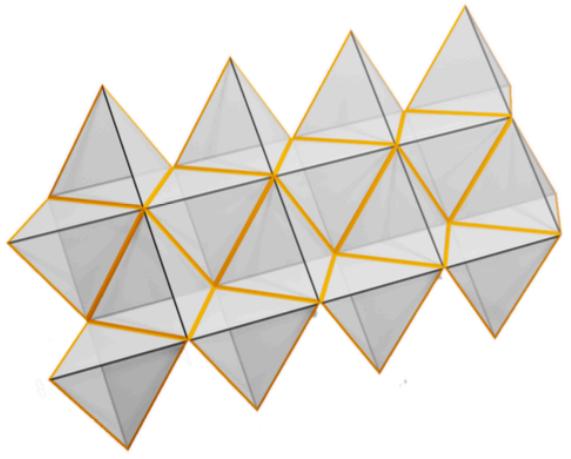
$$\mathbf{B}_2(1, \dots, 1)^\top = 0$$

$$\mathbf{B}_3^\top(1, \dots, 1)^\top = 0$$



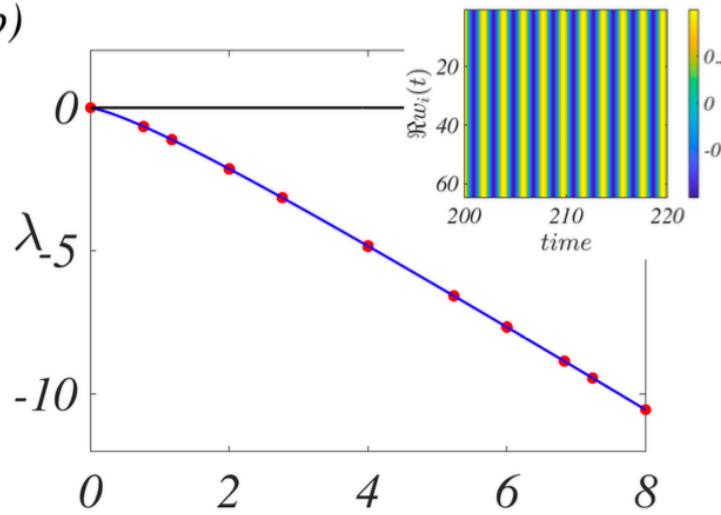
# Global Topological Synchronisation : Stuart-Landau on the waffle

a)



global synch  
for faces ( $k=2$ )

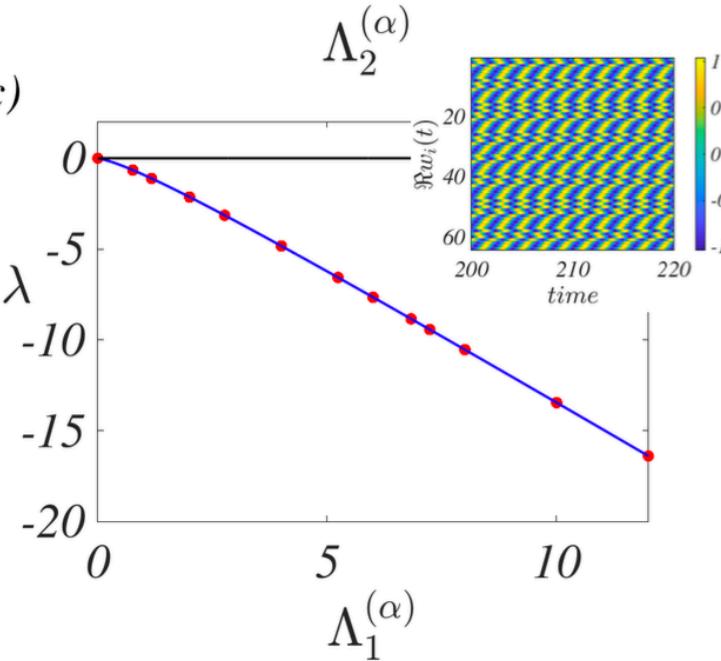
b)



$$\mathbf{B}_2(1, \dots, 1)^\top = 0$$

$$\mathbf{B}_3^\top(1, \dots, 1)^\top = 0$$

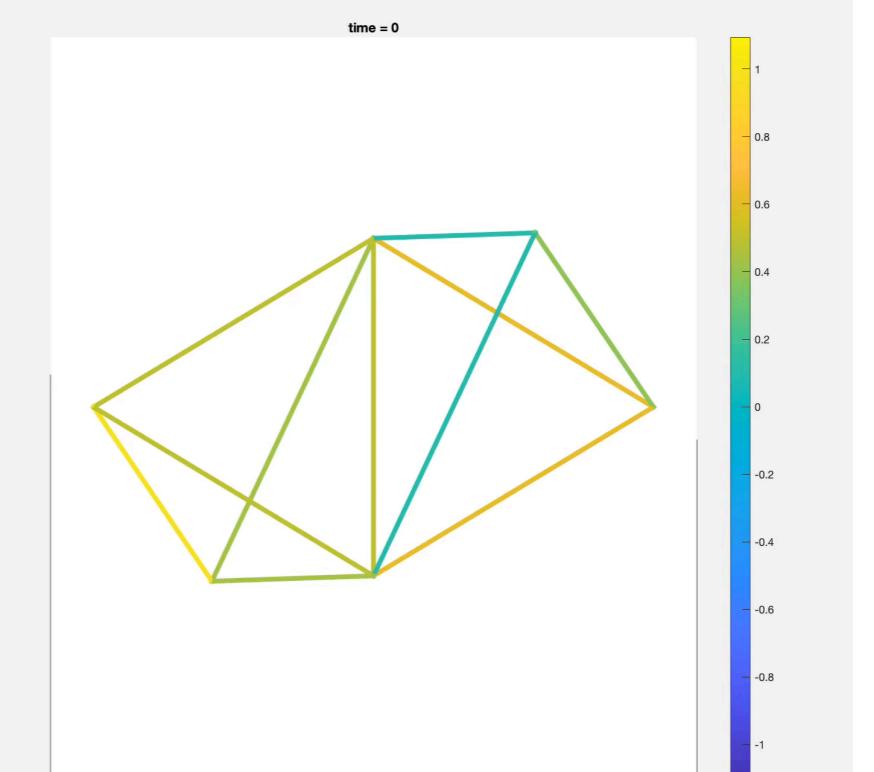
c)



no global synch  
for links ( $k=1$ )

$$\mathbf{B}_1(1, \dots, 1)^\top = 0$$

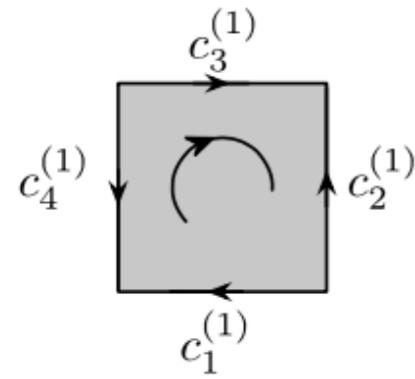
$$\mathbf{B}_2^\top(1, \dots, 1)^\top \neq 0$$



# Global Topological Synchronisation on cell complexes

The topological obstruction  
does not exist for cell complexes

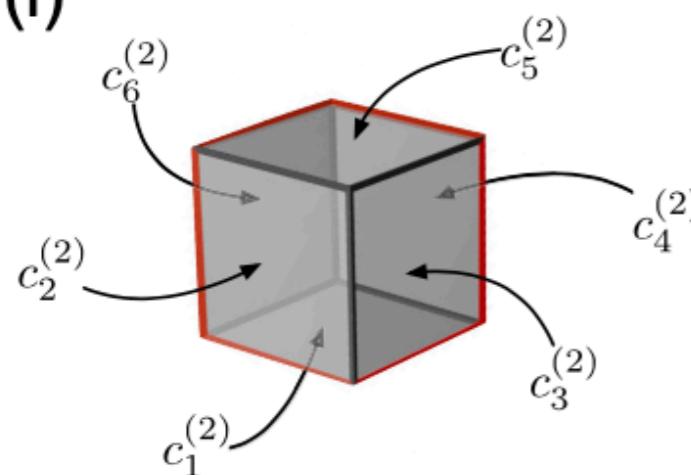
(e)



$$\mathbf{B}_2 = \begin{pmatrix} -1 & \\ & -1 \\ & 1 \\ 1 & \end{pmatrix}$$

$$(1, 1, 1, 1)\mathbf{B}_2 = 0$$

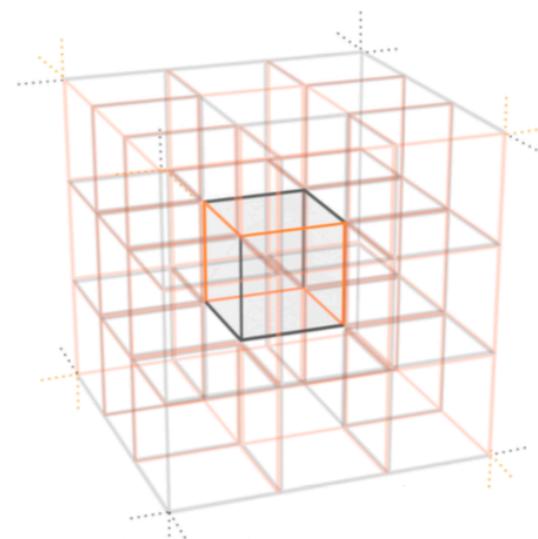
(f)



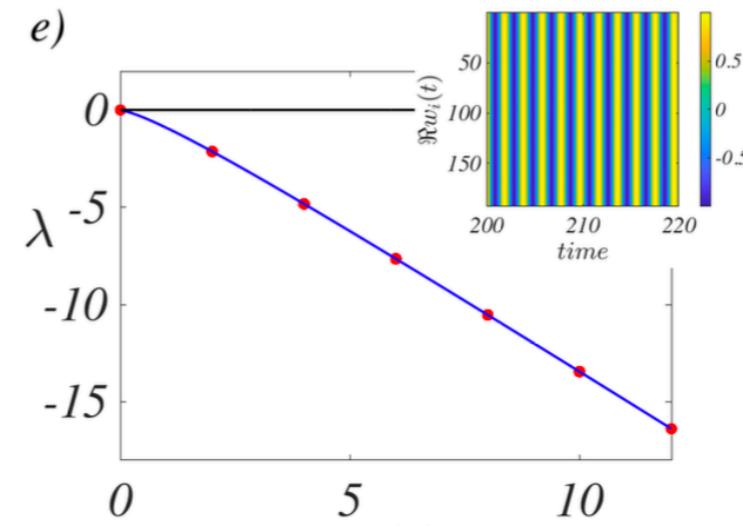
$$\mathbf{B}_3 = \begin{pmatrix} 1 & \\ & -1 \\ & 1 \\ & -1 \\ & 1 \\ & -1 \end{pmatrix}$$

$$(1, 1, 1, 1, 1, 1)\mathbf{B}_3 = 0$$

d)

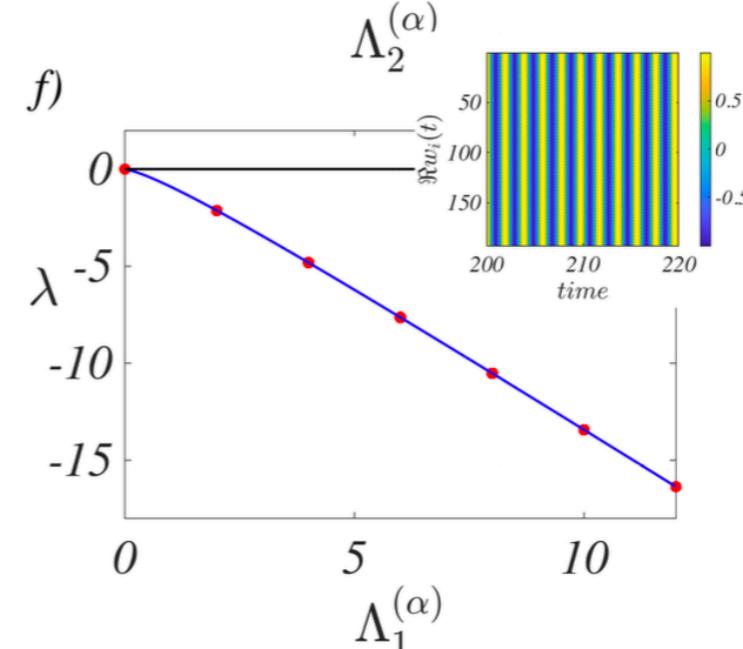


e)



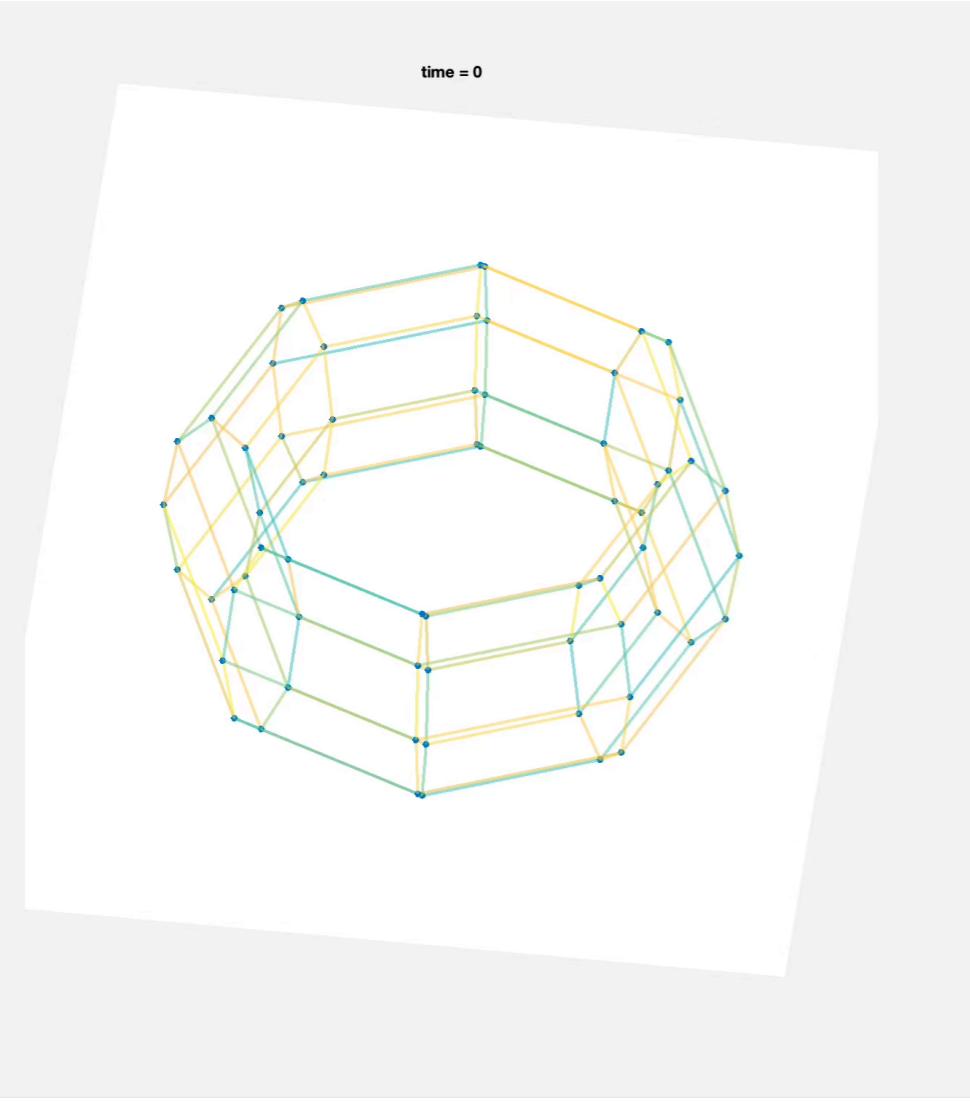
global synch  
for faces

f)

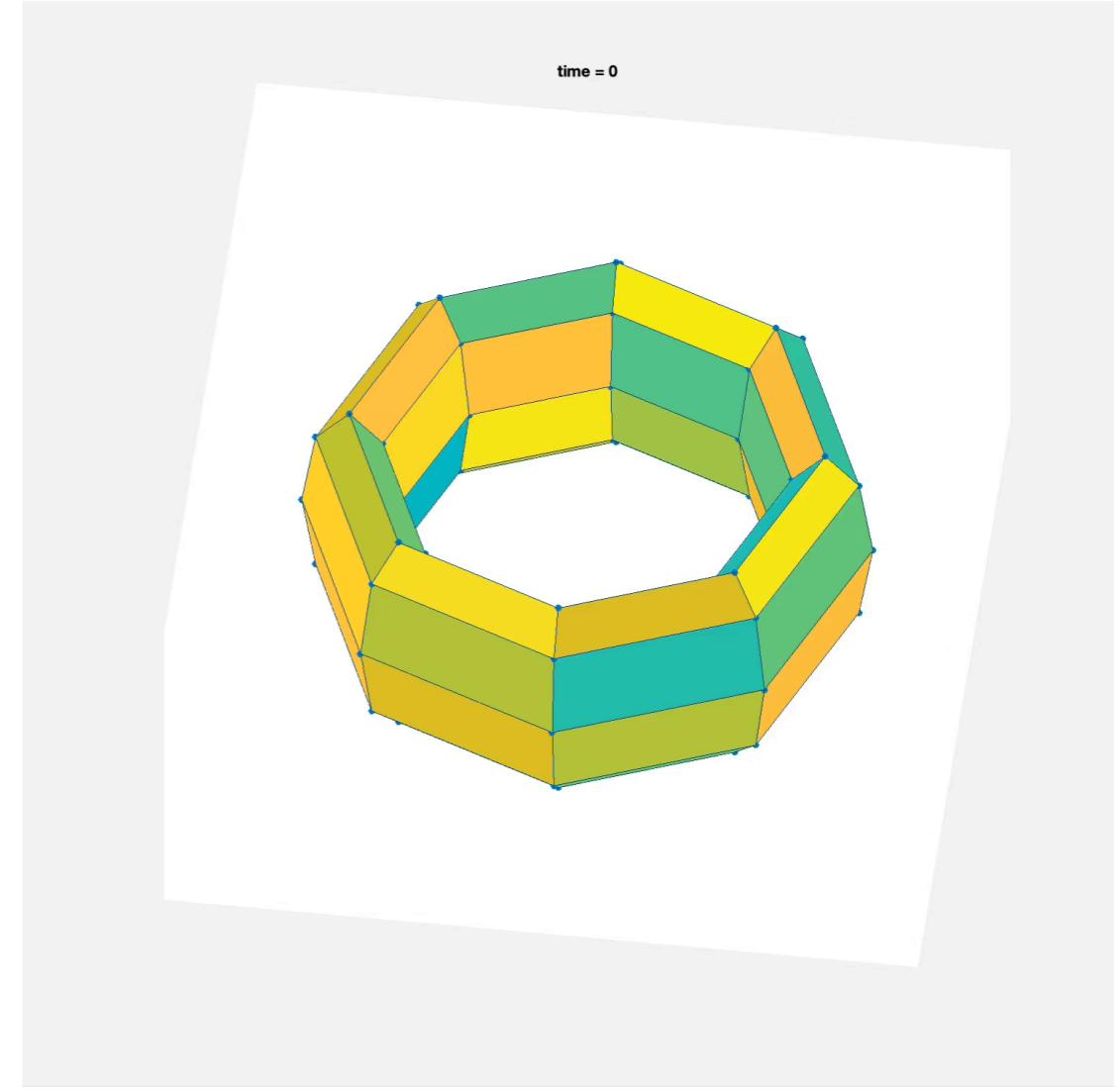


global synch  
for links

# Global Topological Synchronisation on cell complexes



global synch  
for links ( $k=1$ )



global synch  
for faces ( $k=2$ )

October the 2nd, 2024, Ghent, Belgium

Timoteo Carletti

Thank you

Global synchronization on networks  
and beyond

