

Algorithm Tuning Using Optimization

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The context

Two common preoccupations in algorithm design/usage:

- For algorithms designers:

How to tune the parameters of an algorithm in order to ensure the best possible performance on the *largest possible class* of applications?

- For algorithm/code users:

How to tune the parameters of a code in order to ensure the best possible performance on a *specialized class* of applications?

Does achieving the first does help the second?

A way out ?

Some **flexibility** is needed !

- Provide a tuning methodology which is applicable to many algorithms
- Provide code which allows user-tuning for his/her pet problem class

⇒ **optimization?**

- Need to define an **objective function**
(how to measure algorithm performance in this context?)
- Need to define the **constraints** (on algorithmic parameters)
 - simple bounds (algorithm dependent)
 - continuous/integer/categorical variables + mix
(ex: blocking size, model type, ...)

Which objective function?

Assume that the performance $\text{perf}(\text{params}, \text{prob})$ can be measured by running the considered algorithm with parameters params on problem prob .

- First model: optimize the **total/average performance** (AO, **OPAL**):

$$\min_{\text{params}} \sum_{\text{problems}} \text{perf}(\text{params}, \text{prob})$$

- Second model: optimize the **robust performance** (RO):

$$\min_{\text{params}} \max_{\text{perturbed params}} \sum_{\text{problems}} \text{perf}(\text{perturbed params}, \text{prob})$$

where

$$0.95 * \text{params} \leq \text{perturbed params} \leq 1.05 * \text{params}$$

A new tool: BFO (the Brute Force Optimizer)

BFO: a new *local* optimization package with

- randomized pattern search methodology
(does not require continuity of the objective function)
- allows bounds on the variables
- allows continuous/discrete or mixed integer variables
- handles multilevel/equilibrium problems
(needed for the robust tuning strategy)
- includes self-tuning facilities

BFO has been self-tuned

- on a **large set of test problems** (CUTEst) with continuous and mixed-integer variables
- using both the **average** and **robust** tuning strategies
- for all 7 algorithmic parameters

Outcome :

- **robust** strategy slightly better
- gains in performance of
 - **30%** for continuous problems
 - **19%** for mixed-integer problemscompared with "intuitively reasonable values"
- **very competitive with NOMAD** (state-of-the-art pattern search algo)

And then...

... the algorithm designer is (hopefully) **happy** !

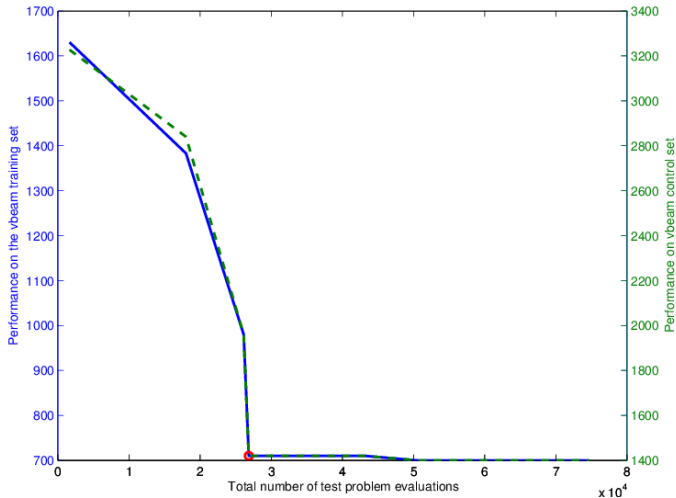
But what about the **user** (with his/her own specific problems)?

BFO allows training by the user for specific problem classes

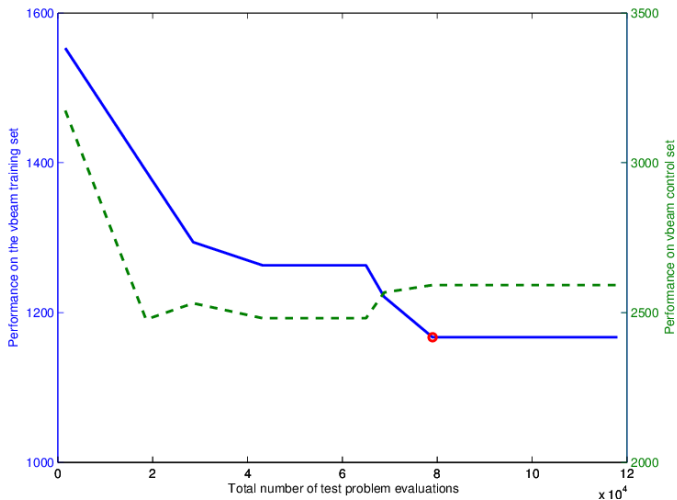
Does this work? Experiment on 3 specific classes of (minimization) problems

- nonlinear nonconvex trajectory tracking least-squares
- nonconvex regularized cubic models

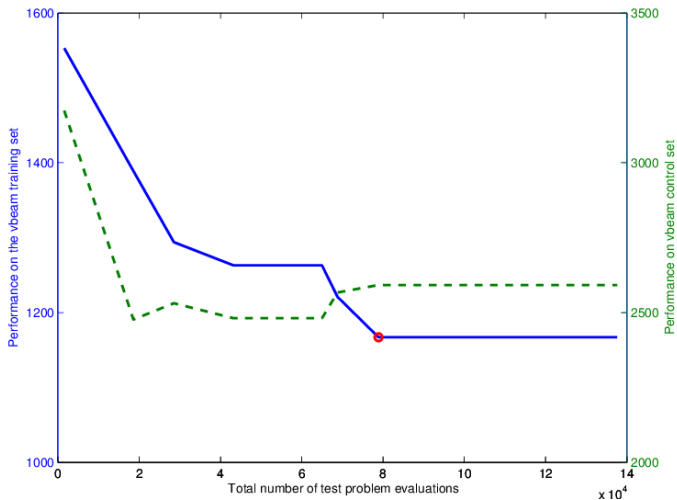
Trajectory tracking: AO training, medium-low error deviation, low accuracy



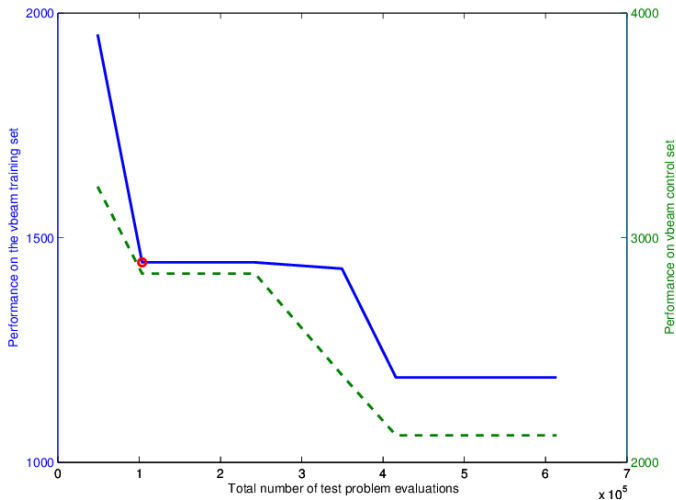
Trajectory tracking: AO training, high error deviation, low accuracy



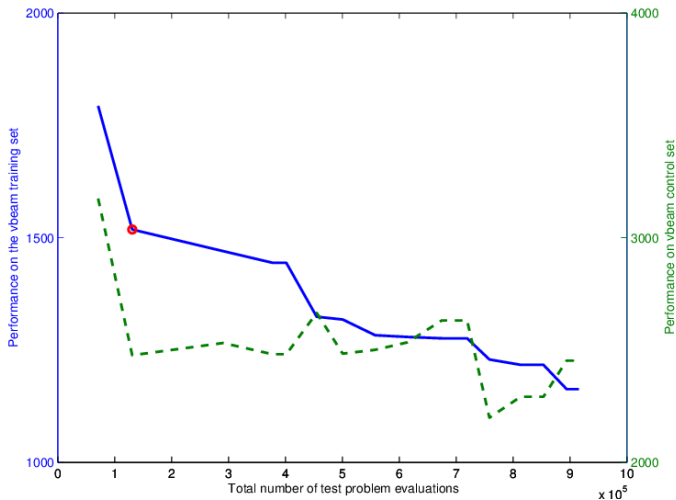
Trajectory tracking: AO training, high error deviation, high accuracy



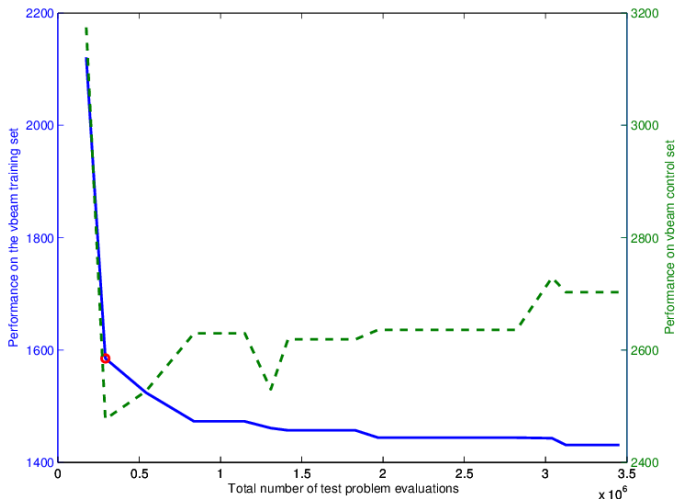
Trajectory tracking: RO training, medium-low error deviation, low accuracy



Trajectory tracking: RO training, high error deviation, low accuracy

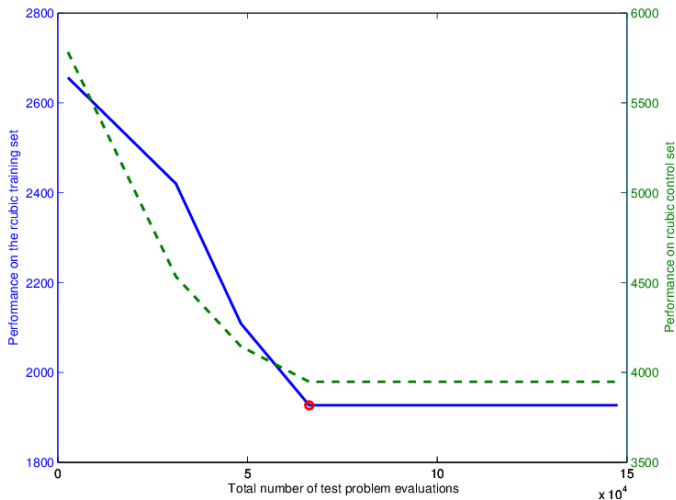


Trajectory tracking: RO training, high error deviation, high accuracy



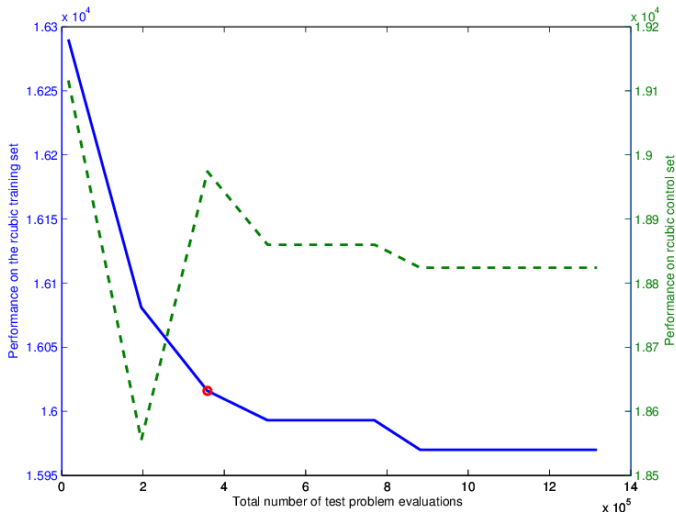
Regularized cubics:

AO training, medium-low error deviation, low accuracy



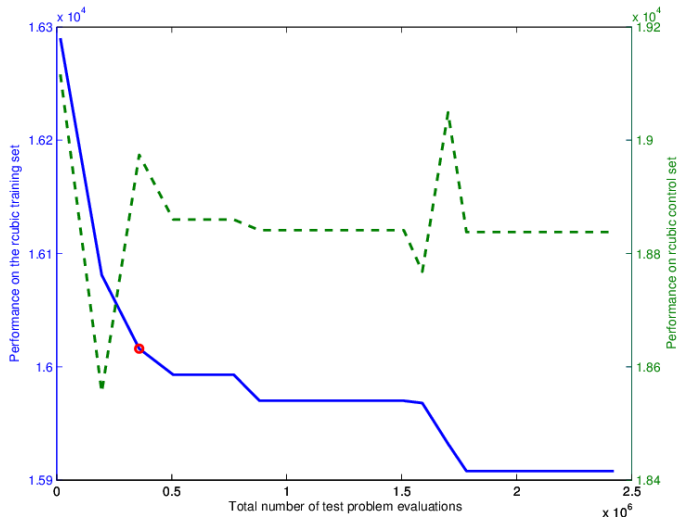
Regularized cubics:

AO training, high error deviation, low accuracy

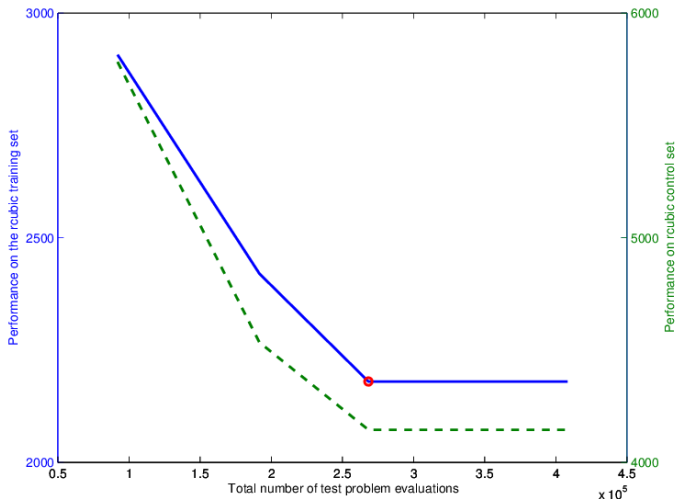


Regularized cubics:

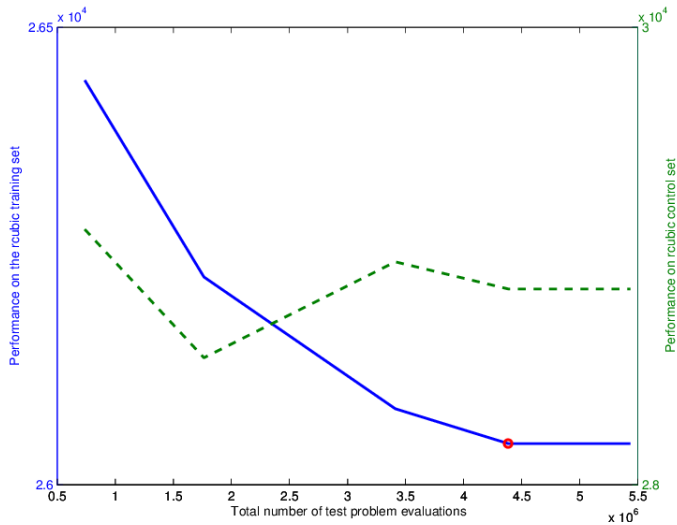
AO training, high error deviation, high accuracy



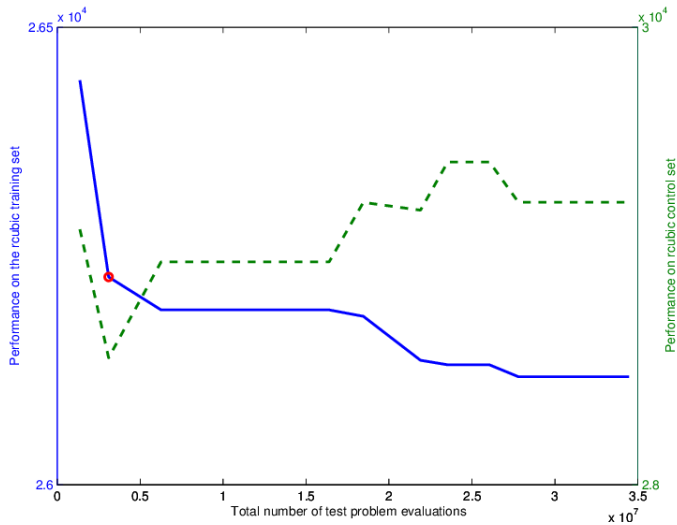
Regularized cubics: RO training, medium-low error deviation, low accuracy



Regularized cubics: RO training, high error deviation, low accuracy



Regularized cubics: RO training, high error deviation, high accuracy



Additional BFO features

- MATLAB code (single file)
- very flexible interface
- optional user-defined variable's scaling
- incomplete function evaluations (crucial for training)
- checkpointing and restart
- flexible termination rules (including objective-function target)
- BFGS finish (for smooth problems)
- direct CUTEst interface

Examples of calls

- `[x, fx] = bfo(@banana, [-1.2, 1])`
- `[x, fx] = bfo(@banana, [-1.2, 1], 'xtype', 'ic')`
- `[x, fx] = bfo(@banana, [-1.2, 1], 'xlower', 0, 'epsilon',0.01)`
- `[x, fx] = bfo(@banana, [-1.2, 1] , ...
 'save-freq',10,'restart-file','bfo.rst')`
- `[x, fx] = bfo(@banana, [-1.2, 1] , ...
 'training-mode', 'train', ...
 'training-parameters', 'fruity', ...
 'training-problems', {@banana,@apple},...
 'training-problems-data', {@fruit_data})`
- `[x, fx] = bfo(@robust_training, [0, -1, 0, 1] , ...
 'xlevel', [1 1 2 2], ...
 'max-or-min', ['min', 'max'])`

Some conclusions

- `*** Use BFO to tune your algorithm! ***`

(you can even tune BFO to tune your own algorithms)

- The future: more complicated constraints, ...

- `More user-tunable codes?`

Many thanks for your attention!